

as a technique for random sampling

Random sampling via Markov chain

マルコフ連鎖を用いたランダムサンプリング法

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In this talk,
'sampling' = 'random sampling'

-7. Sampling via Markov chain

key word

Markov chain Monte Carlo (MCMC)

<narrowly defined as>

Monte Carlo method with sampling via Markov chain

<comprehensively intend>

sampling via Markov chain

Markov chain

- Markov chain M (ergodic) defined by
 - state space: $\Omega = \{s_1, s_2, s_3\}$ (finite)
 - transition: transition probability matrix P

$$P_{ij} = \Pr(i \rightarrow j) =: P(i, j)$$

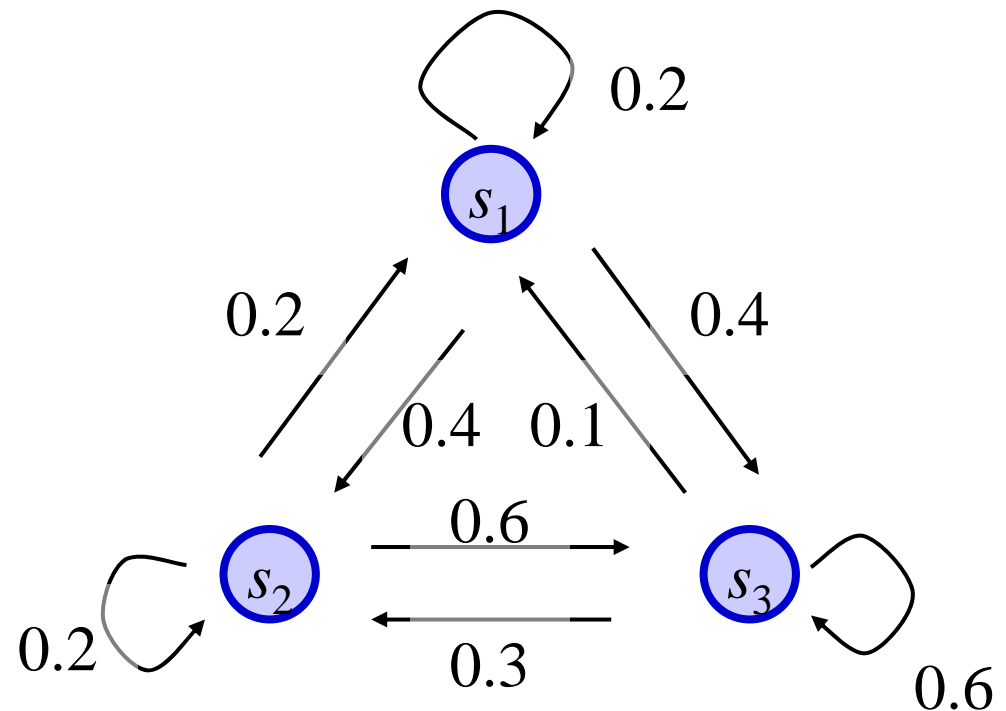


figure shows an ex. of
prob. trans. diagram of Markov chain

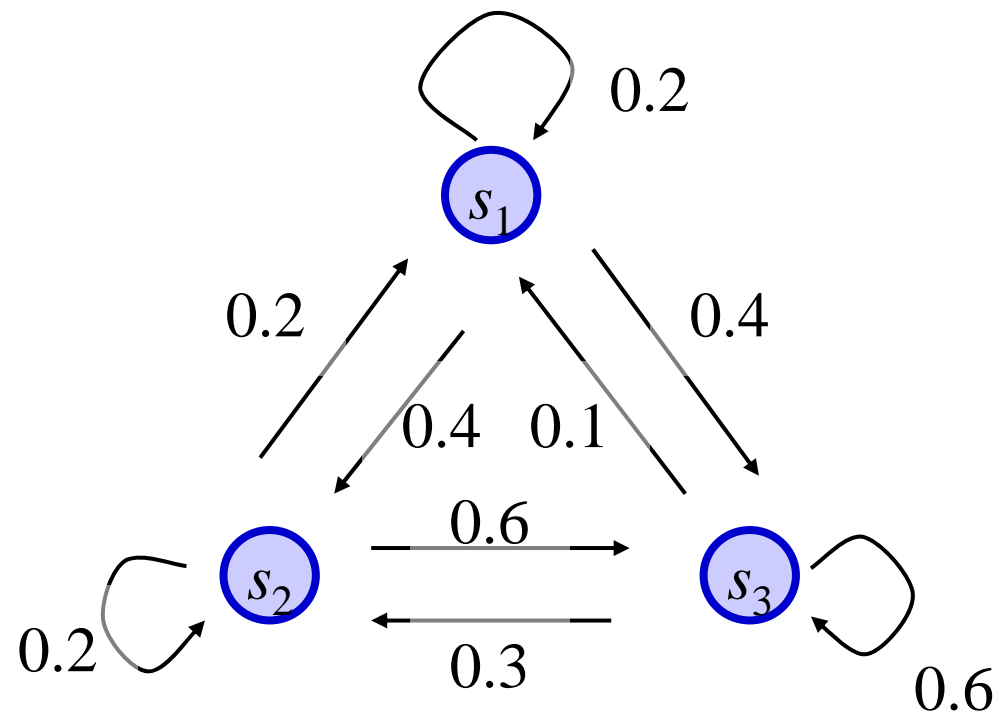
Markov chain

- Markov chain M (ergodic)

- **state space**: $\Omega = \{s_1, s_2, s_3\}$ (finite)
- **transition**: transition probability matrix P

$$P_{ij} = \Pr(i \rightarrow j) =: P(i, j)$$

current state	next state		
	s_1	s_2	s_3
s_1	0.2	0.4	0.4
s_2	0.2	0.2	0.6
s_3	0.1	0.3	0.6

$$P = \begin{pmatrix} 0.2 & 0.4 & 0.4 \\ 0.2 & 0.2 & 0.6 \\ 0.1 & 0.3 & 0.6 \end{pmatrix}$$


underlying graph

Stationary distribution

- Markov chain M (ergodic)

- state space: $\Omega = \{s_1, s_2, s_3\}$ (finite)

- transition: transition probability matrix P

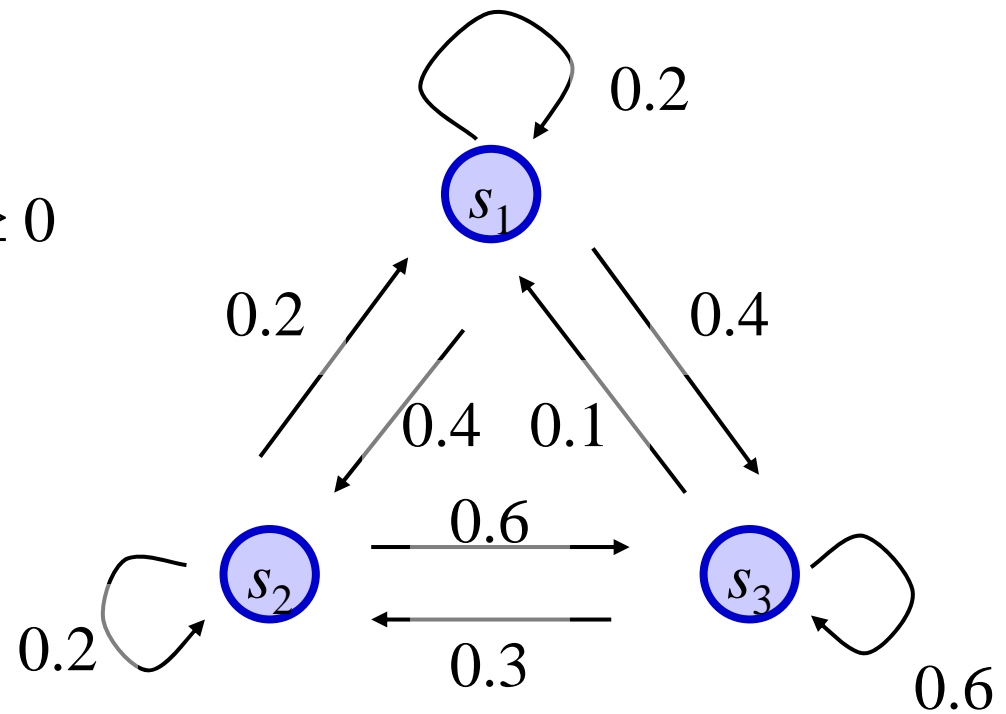
$$P_{ij} = \Pr(i \rightarrow j) =: P(i, j)$$

- stationary distribution: π

$$\Leftrightarrow \pi P = \pi, \quad |\pi| = 1, \quad \pi \geq 0$$

$$P = \begin{pmatrix} 0.2 & 0.4 & 0.4 \\ 0.2 & 0.2 & 0.6 \\ 0.1 & 0.3 & 0.6 \end{pmatrix}$$

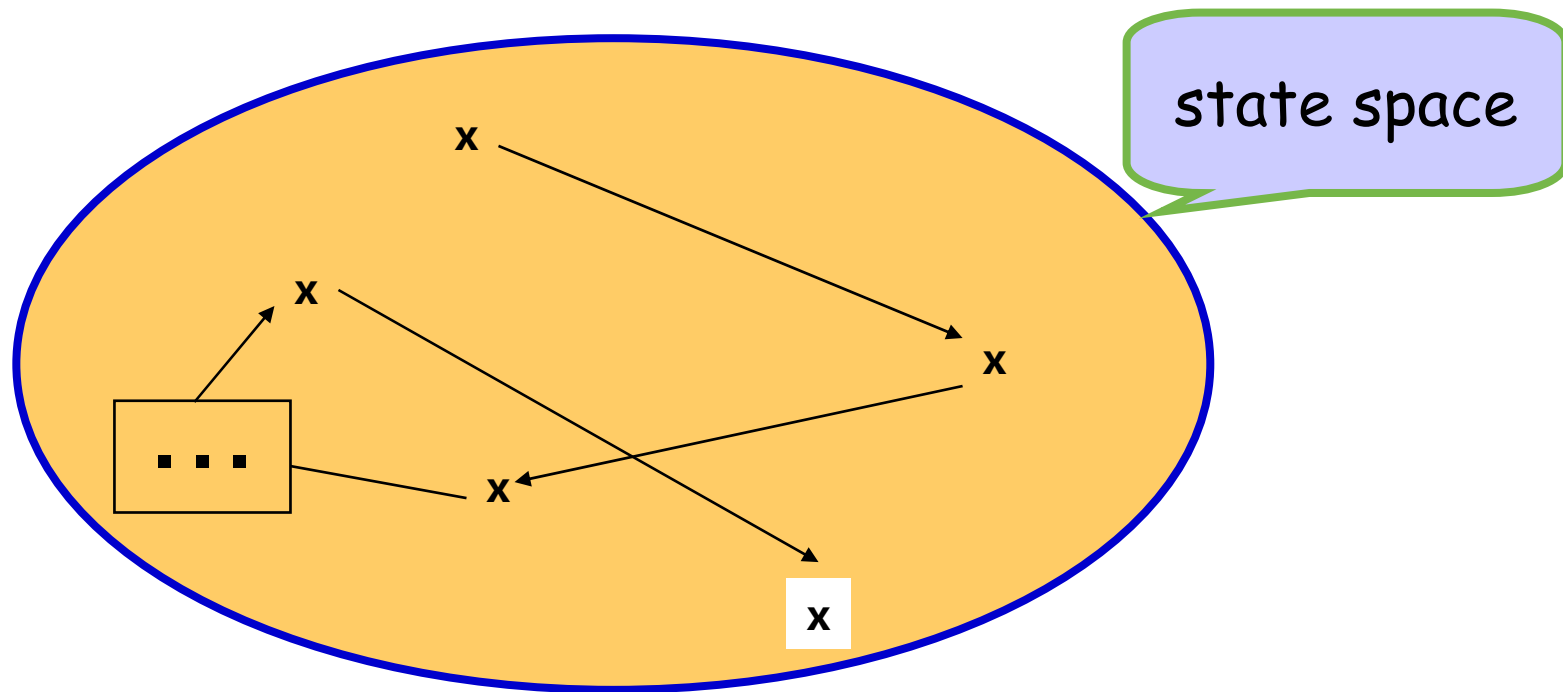
$$\pi = (1/7, 2/7, 4/7)$$



underlying graph

Basic idea of "sampling via Markov chain"

1. Design a Markov chain whose stat. dist = aiming dist.
2. Generate a sample from stat. dist. after many tran.s.



outputs after many transitions according to asymptotically **stationary distribution**

Applications of MCMC

- counting-hard
- huge state space

MCMC works powerfully for **sampling-hard** objects

➤ Easy to design a sampler for an objective distribution

cf) simulated annealing

$\Pr[\text{global opt.}] = 1$
 $\Pr[\text{other sol.s}] = 0$

➤ Many applications

- Contingency table
- Ising model
- Permanent
- Spanning tree
- Numerical integration (Monte Carlo integration)
- Optimization

in this talk, deal with

Ex. 1. Contingency table

as an ex. of sampling via Markov chain

8

- ✓ matrix of non-negative integers
- ✓ satisfies (given) marginal sums

						12
						18
5	4	3	7	5	6	30

Problem

Given: **marginal sums**

Output: a contingency table **u.a.r.**

Ex. 1. Contingency table

- ✓ matrix of non-negative integers
- ✓ satisfies (given) marginal sums

						12
						18
5	4	3	7	5	6	30

5	4	3	0	0	0	12
0	0	0	7	5	6	18
5	4	3	7	5	6	30

table A

4	3	1	3	1	0	12
1	1	2	4	4	6	18
5	4	3	7	5	6	30

table B

0	0	0	1	5	6	12
5	4	3	6	0	0	18
5	4	3	7	5	6	30

table C

Problem

Given: **marginal sums**

Output: a contingency table **u.a.r.**

Ex. 1. Contingency table

- ✓ matrix of non-negative integers
- ✓ satisfies (given) marginal sums

						12
						18
5	4	3	7	5	6	30

counting # of tables satisfying given marginal sums

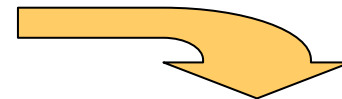
⇒ #P-complete (NP-hard), even when size of table is $2 \times n$

[Dyer, Kannan, and Mount '97]

Problem

Given: **marginal sums**

Output: a contingency table **u.a.r.**



sampling via
Markov chain

Previous works of contingency tables

1985, Diaconis and Effron, **exact test** with uniform sampler ,

1995, Diaconis and Saloff-Coste, **approx. sampler** for $m^* \times n^*$ table,

1997, Dyer, Kannan and Mount, **#P-completeness**,

2000, Dyer and Greenhill, **approx. sampler** for $2 \times n$ table,

2002, Cryan et al., **approx. sampler** for $m^* \times n$ table

2003, Kijima and Matsui, **perfect sampler** for $2 \times n$ table

Open problem

Is there a poly-time (approx. or perfect) sampler for $m \times n$ table?

Basic idea of "sampling via Markov chain"

1. Design a Markov chain whose stat. dist = aiming dist.
2. Generate a sample from stat. dist. after many tran.s.



-6: Design of Stationary Distribution

Design of Markov chain with aiming stat. dist.

A Markov chain M is **ergodic**, iff

1. the state space is finite,
2. trans. matrix is **irreducible**, and
3. **aperiodic**.

limit dist. = stat. dist.

every pair is mutually reachable

Then

For a positive function f and transition prob. matrix P ,
if **detailed balance equations**

$$f(x) \cdot P(x, y) = f(y) \cdot P(y, x) \quad \forall x, y \in \Omega$$

hold, then the stationary distribution

$$\pi(x) = c \cdot f(x)$$

c is the normalizing constant

Metropolis-Hastings, Gibbs sampler, heat-bath chain, etc.

Ex. 1. Markov chain for contingency tables [KM '06]

transition rule is defined as follows

1. choose a **consecutive** pair of columns $(j, j+1)$ u.a.r. (prob. $1/(n-1)$)
2. change the values of cells in $(j, j+1)$ -th columns u.a.r. on possible states

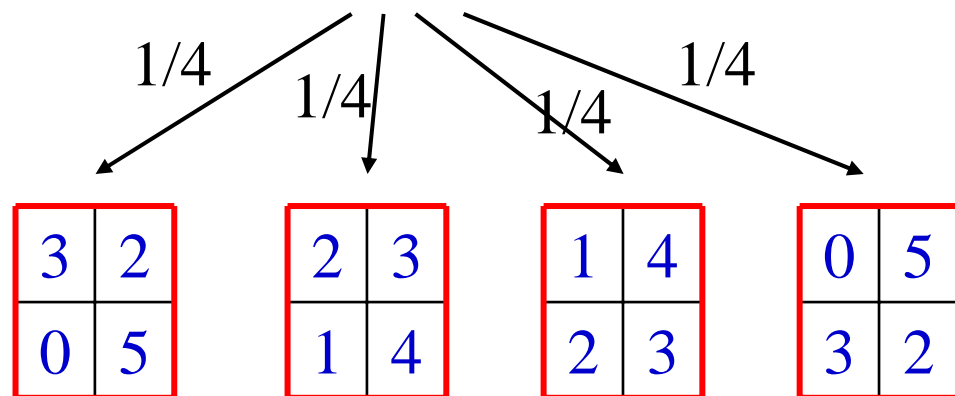
2	3	5
1	4	5
3	7	10

+

$+k$	$-k$
$-k$	$+k$

=> preserve marginal sums

		j	$j+1$			
		↓	↓			
4	3	2	3	0	0	12
1	1	1	4	5	6	18
5	4	3	7	5	6	30



4 possible states

(requirement on non-negativity)

Our Markov chain for contingency tables [KM '06]

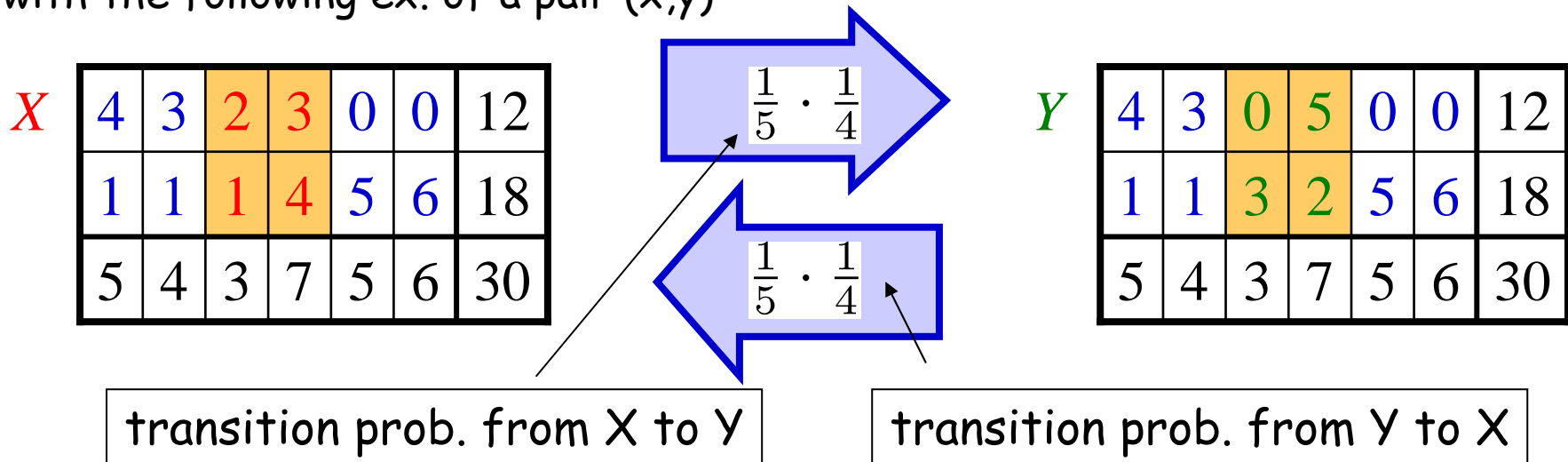
Them

Our Markov chain is ergodic, and
the unique stat. dist. of the chain is uniform dist.

proof for the latter claim: **detailed balance equations**

$$1 \cdot P(x, y) = 1 \cdot P(y, x) \quad \forall x, y \in \Omega \quad \text{hold.}$$

with the following ex. of a pair (x, y)



since ...

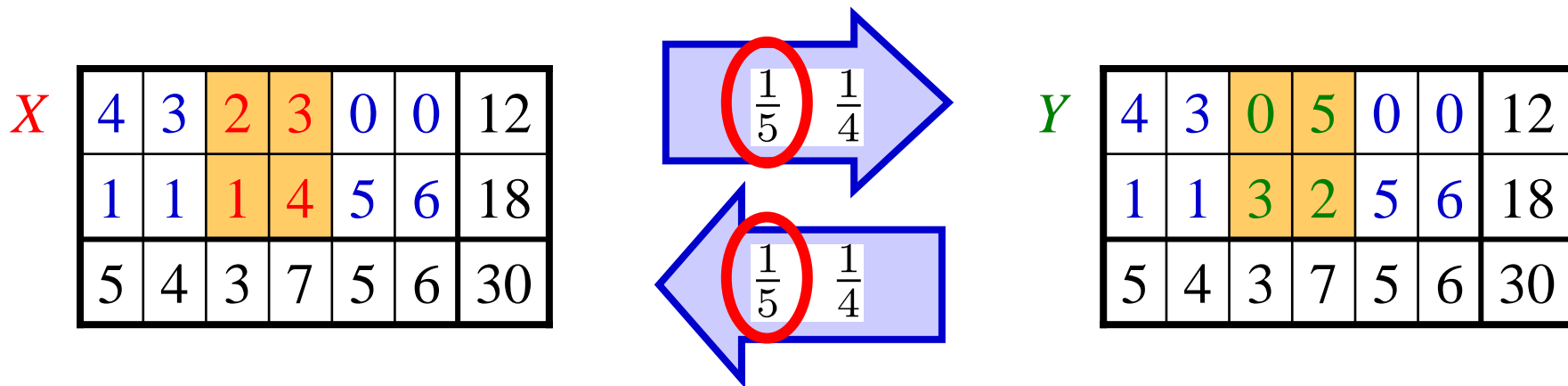
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$$1 \cdot P(x, y) = 1 \cdot P(y, x) \quad \forall x, y \in \Omega \quad \text{hold.}$$



choose a consecutive pair of indices u.a.r. (w.p. $1/(6-1)$)

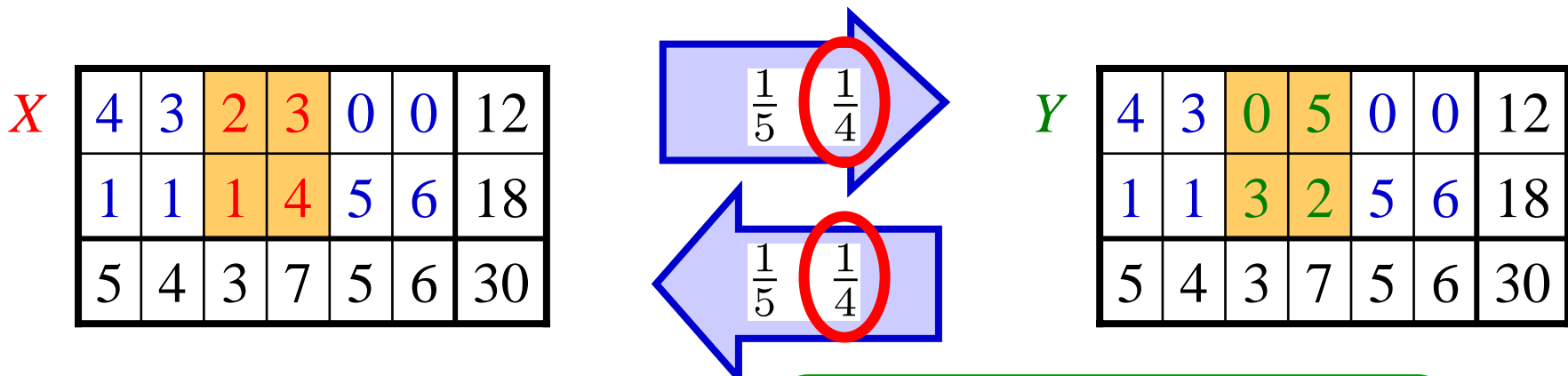
Our Markov chain for contingency tables [KM '06]

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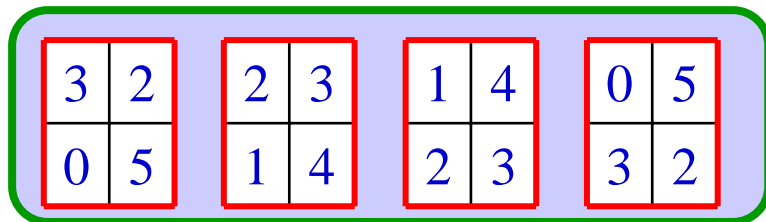
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$$1 \cdot P(x, y) = 1 \cdot P(y, x) \quad \forall x, y \in \Omega \quad \text{hold.}$$



on the condition (3,4) columns are chosen,
there are common 4 possible states,
since values in other columns are same.



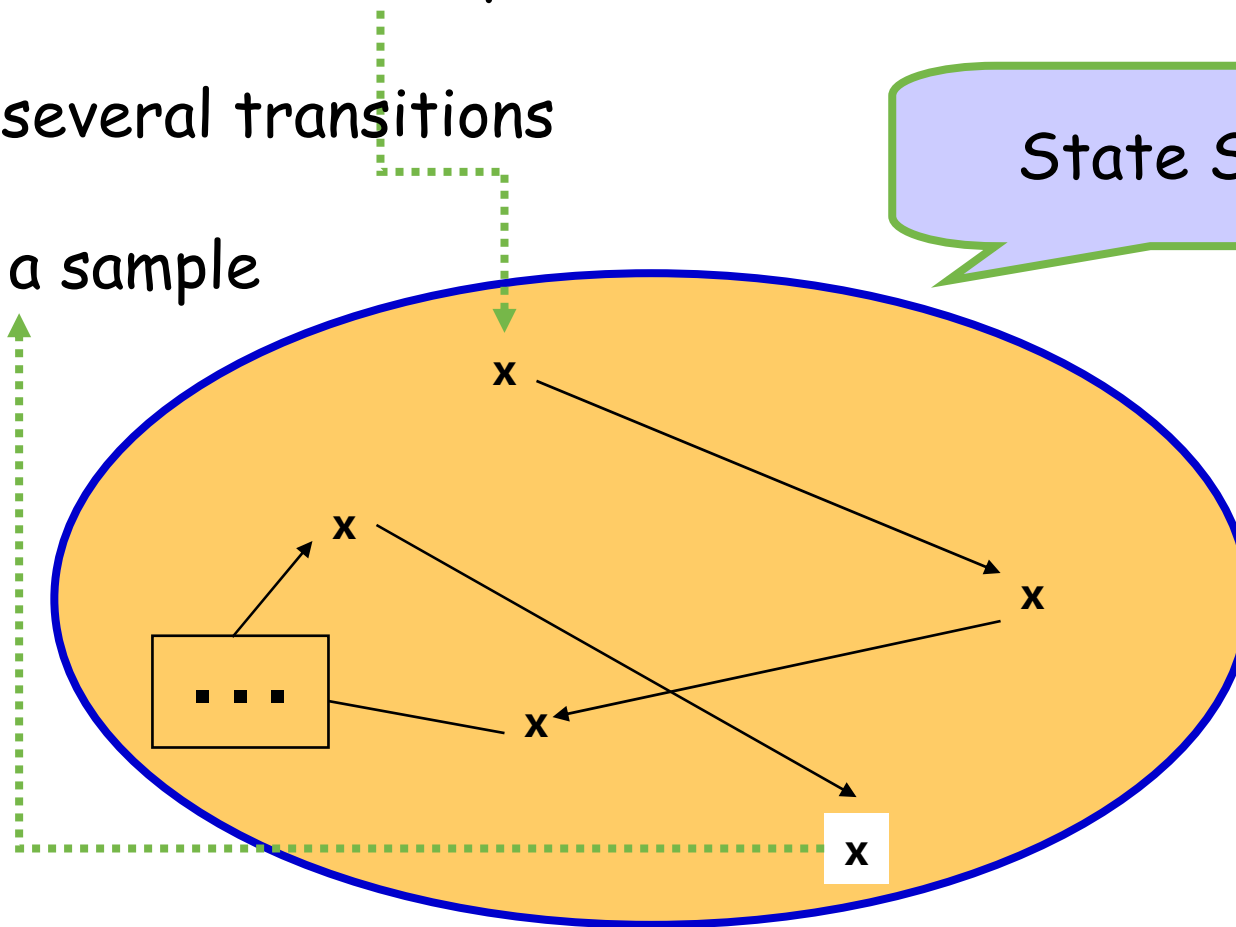
Basic idea of sampling via Markov chain

Start from arbitrary initial state

Make several transitions

Output a sample

State Space



The output is 'approximately' according to the **stat. dist.**

Basic idea of "sampling via Markov chain"

1. Design a Markov chain whose stat. dist = aiming dist.
2. Generate a sample from stat. dist. after many tran.s.



-5: Convergence Speed of Markov chain

frontier of MCMC

"How many transitions do we need?"

make the error sufficiently small

- If we have an **approximate sampler**,
 - we have to estimate the **mixing time**, and
 - bound the **total variation distance**.

- If we have a **perfect sampler**,

- we can output a sample

No error

exactly according to the stationary distribution.

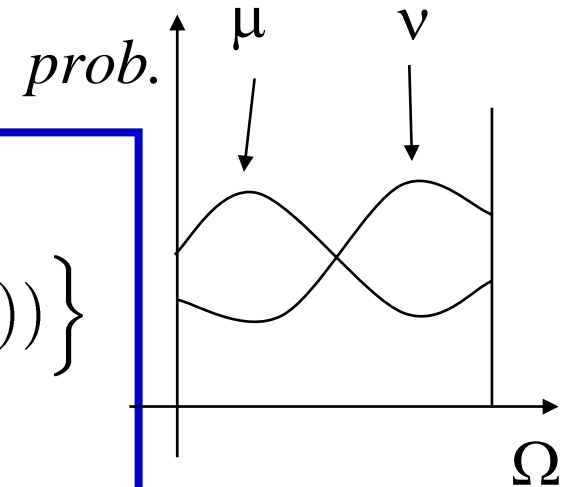
We need not to decide the error rate.

- **CFTP** (Coupling From The Past) realizes a perfect sampler

Mixing time of a Markov chain is defined as follows

μ, ν : dist. on Ω

Error



Total variation distance

$$d_{\text{TV}}(\mu, \nu) \stackrel{\text{def.}}{=} \max_{Q \subseteq \Omega} \left\{ \sum_{x \in Q} (\mu(x) - \nu(x)) \right\}$$

$$\equiv \frac{1}{2} \sum_{x \in \Omega} |\mu(x) - \nu(x)|$$

Ergodic chain M (stat. space Ω , trans. matrix P , stat. dist. π)

Mixing time

t.v.d. is proved sufficiently small in mixing time

$$\tau(\varepsilon) \stackrel{\text{def.}}{=} \max_{x \in \Omega} \left\{ \min \{ t \mid \forall s \geq t, d_{\text{TV}}(P_x^t, \pi) \leq \varepsilon \} \right\}$$

➤ **rapidly mixing** if $\tau(\varepsilon) \leq \text{poly.}(\log \Omega, \varepsilon^{-1})$

"How many transitions do we need?"

make the error sufficiently small

- If we have an **approximate sampler**,
 - we have to estimate the **mixing time**, and
 - bound the **total variation distance**.

- If we have a **perfect sampler**,

- we can output a sample

NO ERROR

exactly according to the stationary distribution.

We need not to decide the error rate.

- **CFTP** (Coupling From The Past) realizes a perfect sampler

INTERMEZZO

review of

-3. PERFECT SIMULATION

Propp and Wilson [1996]

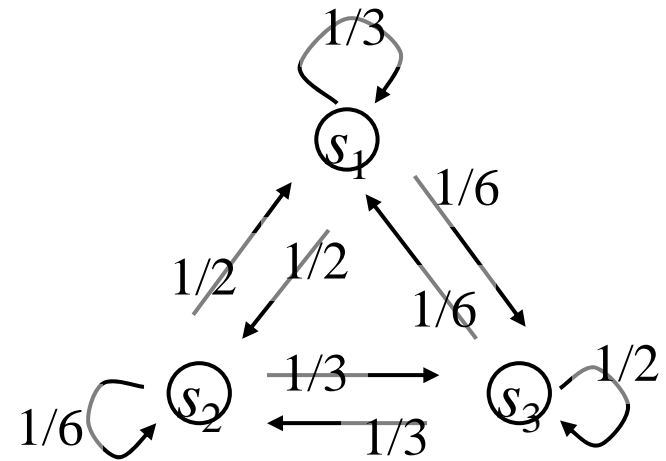
The coupling from the past (CFTP)

- is an ingenious simulation of Markov chain,
- which realize perfect sampling.

sampling from EXACTLY limit distribution

Update function -- with an example

- An ergodic Markov chain MC
 - finite state space: s_1, s_2, s_3 ;
 - Transition



Update function -- with an example

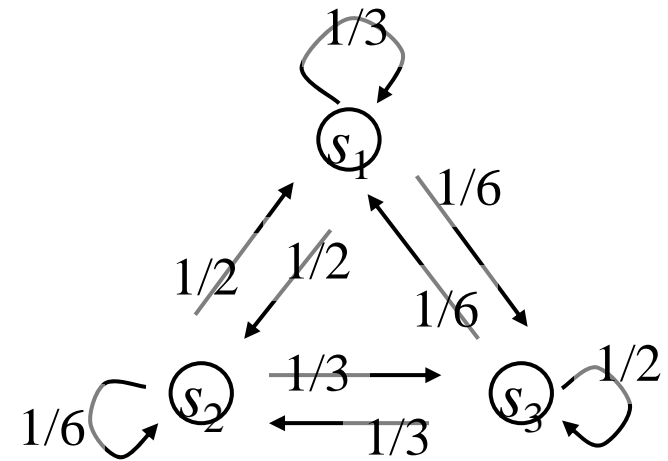
- An ergodic Markov chain MC

We consider to determine the next state with

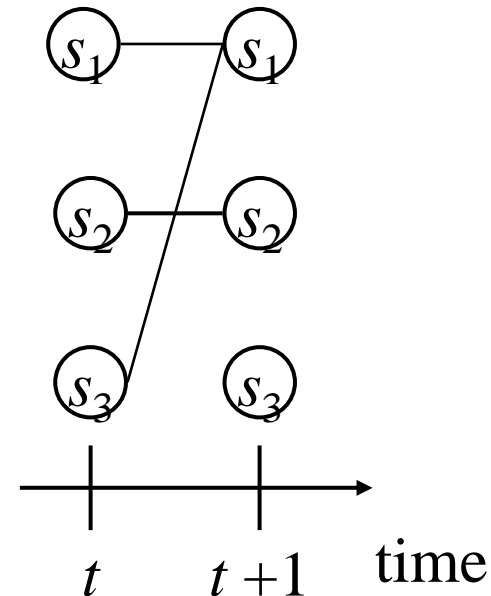
- a random number $\lambda \in \{1, \dots, 6\}$ (u.a.r.), and
- an **Update function**.

		current state		
		s_1	s_2	s_3
λ	1	s_3	s_1	s_2
	2	s_2	s_3	s_2
	3	s_2	s_1	s_3
	4	s_1	s_1	s_3
	5	s_1	s_2	s_1
	6	s_2	s_3	s_3

This table shows an update function



e.g., 5 $\leftarrow \lambda$



This is an illustration of a transition.

CFTP Algorithm and Theorem.

Markov chain MC : $\left\{ \begin{array}{l} \Omega: \text{finite state space} \\ \Phi_s^t(x, \lambda): \text{transition rule} \\ \text{ergodic} \end{array} \right.$

CFTP Algorithm

1. Set $T = -1$; set λ : empty;
2. Generate $\lambda[T]$: random number;
Put $\lambda := (\lambda[T], \lambda[T+1], \dots, \lambda[-1])$;
3. Start a chain from every element in Ω at period T , run MC with λ to period 0.
 - a. if **coalesce** ($\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda)$) \Rightarrow return y ;
 - b. otherwise, set $T := T-1$; go to step 2.;

consists of

- 3 steps and
- a stopping condition

CFTP Theorem

When CFTP Algorithm terminates, the returned value realizes the random variable from stationary distribution, **exactly**.

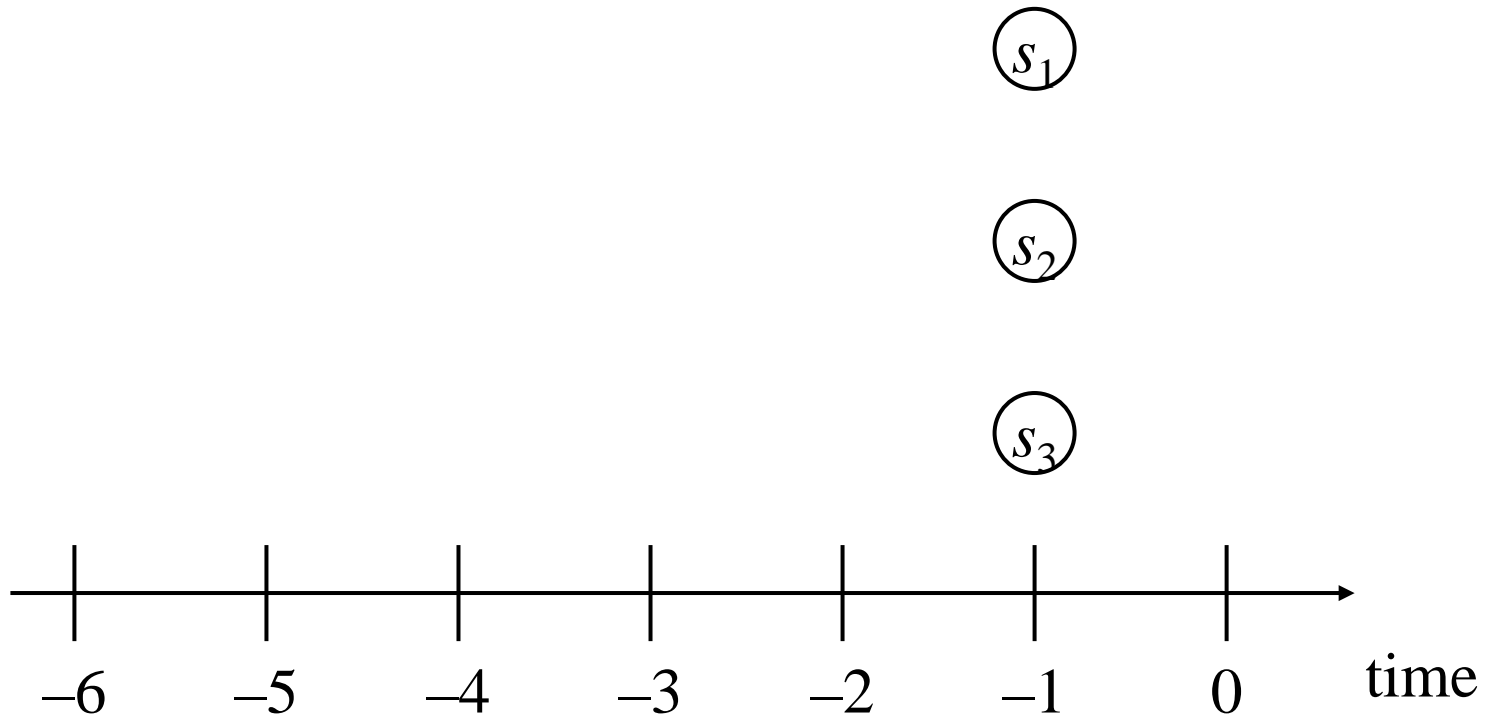
In the following slides, I will illustrate the algorithm precisely.

Simulation from $T = -1$

1. set $T = -1$; set λ : empty sequence;

Step 1 is an initializing step

← λ



Simulation from $T = -1$

2. Generate $\lambda[T]$: random number;

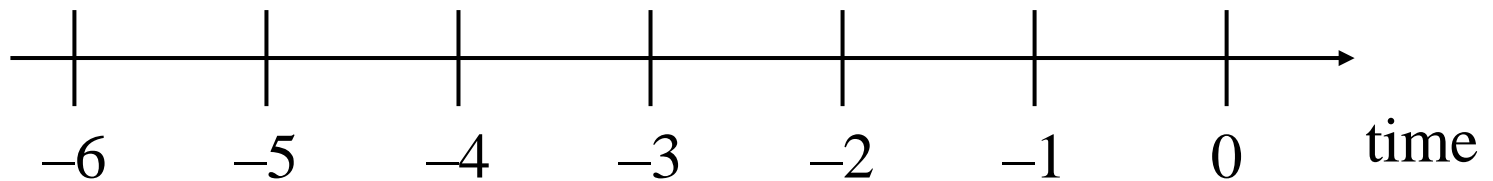
Put $\lambda := (\lambda[T], \lambda[T+1], \dots, \lambda[-1])$;

$$\lambda(-1) = 5 \quad \leftarrow \lambda$$

s_1

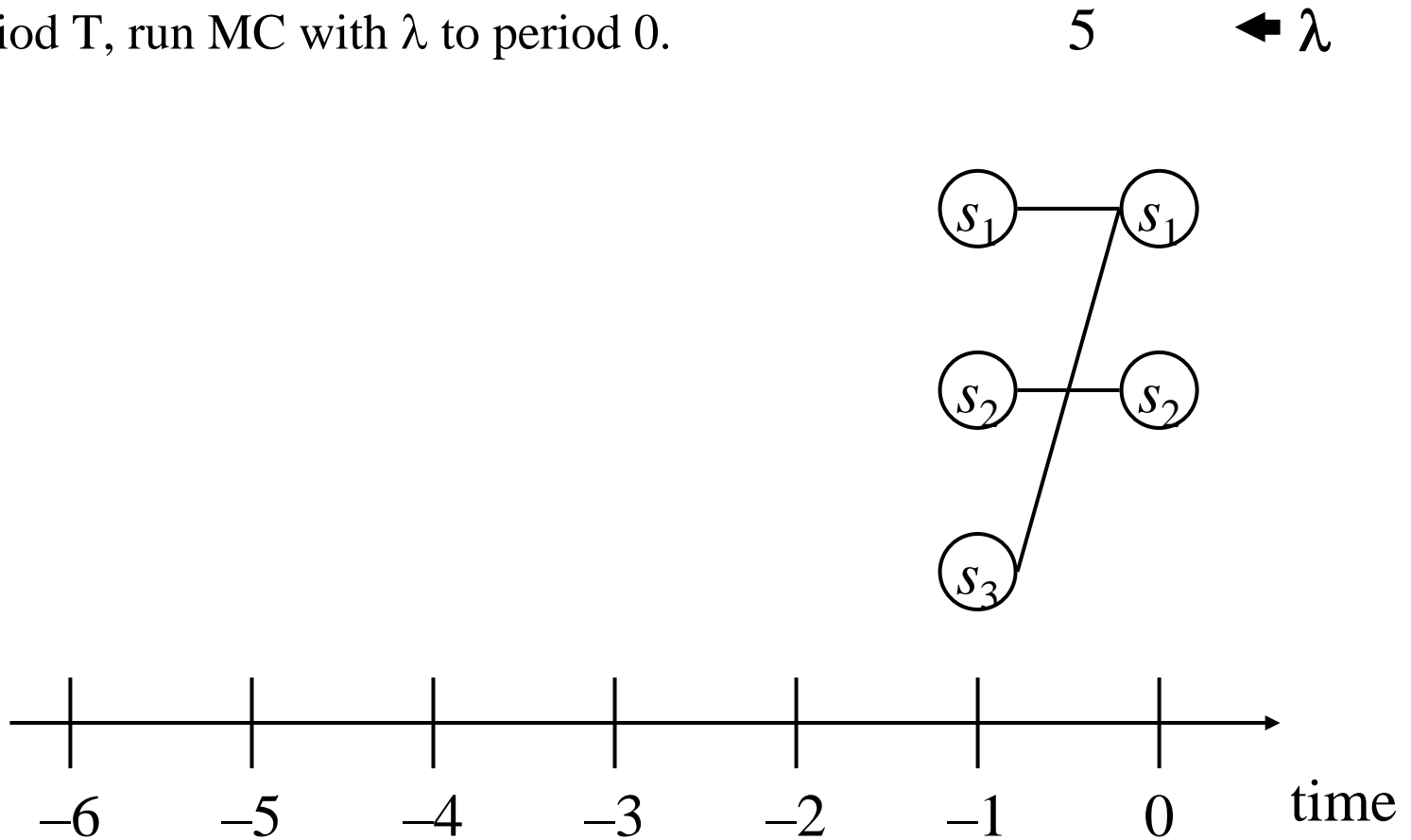
s_2

s_3



Simulation from $T = -1$

3. Start a chain from every element in Ω
at period T , run MC with λ to period 0.



Simulation from $T = -1$

3. Start a chain from every element in Ω
at period T , run MC with λ to period 0.

a. if **coalesce**

$$(\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda))$$

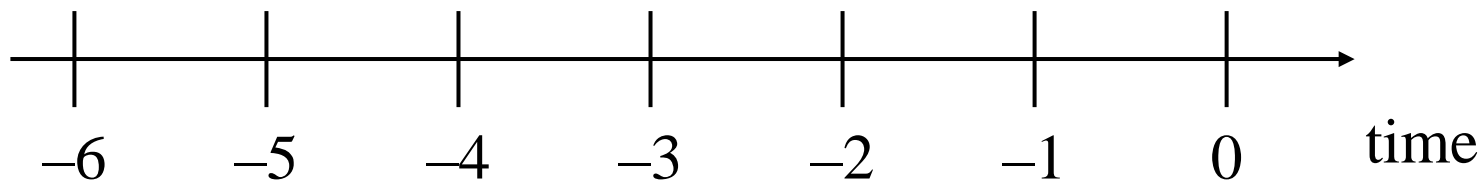
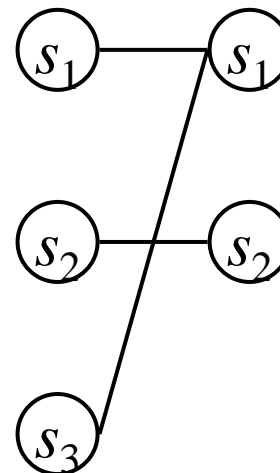
\Rightarrow return y ;

b. otherwise, set $T := T - 1$;

go to step 2.;

coalesce means
a state at 0 is unique.

5 $\leftarrow \lambda$



In this case, the states do not coalesce, thus...

Simulation from $T = -2$

3. Start a chain from every element in Ω
at period T , run MC with λ to period 0.

5 ← λ

a. if **coalesce**

$$(\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda))$$

⇒ return y ;

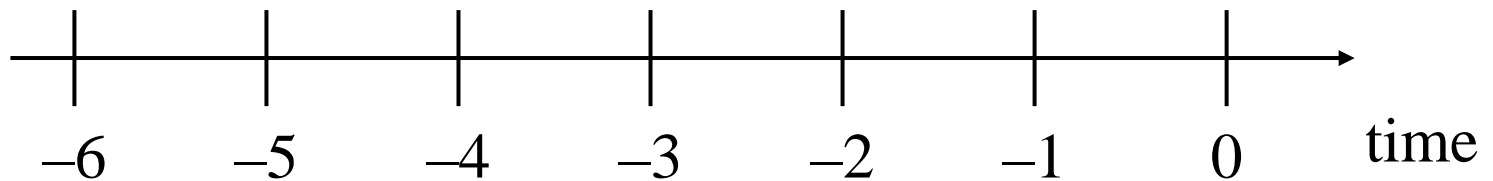
b. otherwise, set $T := T - 1$;

go to step 2.;

s_1

s_2

s_3



Simulation from $T = -2$

2. Generate $\lambda[T]$: random number;

Put $\lambda := (\lambda[T], \lambda[T+1], \dots, \lambda[-1])$;

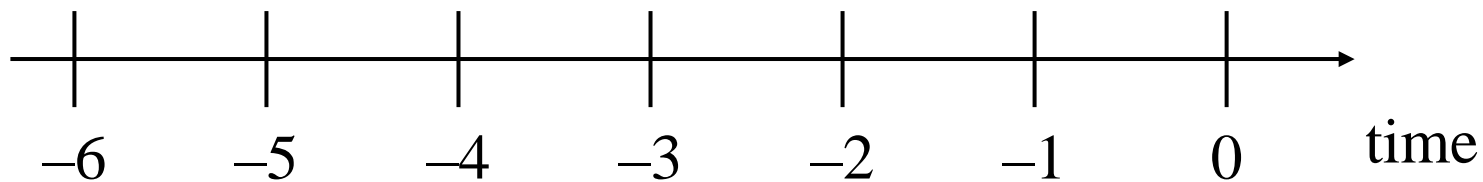
We will use "5" from -1 to 0 again,
generated in the previous iteration.

$$\lambda(-2) = 2 \quad 5 \quad \leftarrow \lambda$$

s_1

s_2

s_3



Simulation from $T = -2$

3. Start a chain from every element in Ω
at period T , run MC with λ to period 0.

a. if **coalesce**

$$(\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda))$$

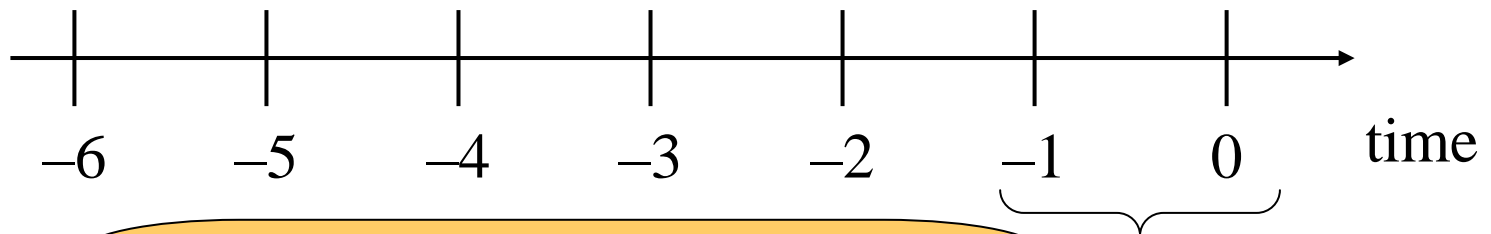
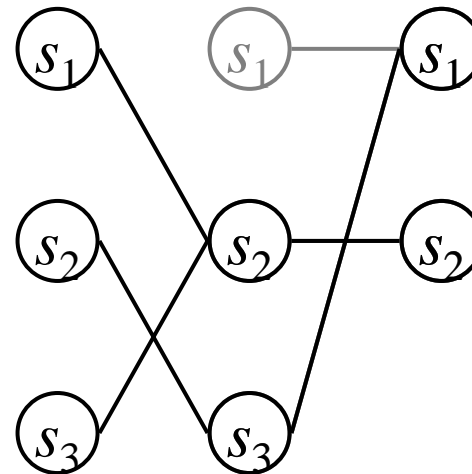
\Rightarrow return y ;

b. otherwise, set $T := T - 1$;

go to step 2.;

We will use "5" from -1 to 0 again,
generated in the previous iteration.

2 5 $\leftarrow \lambda$



Note

transitions from -1 to 0

= transitions in the previous iteration

Simulation from $T = -3$

a. if **coalesce**

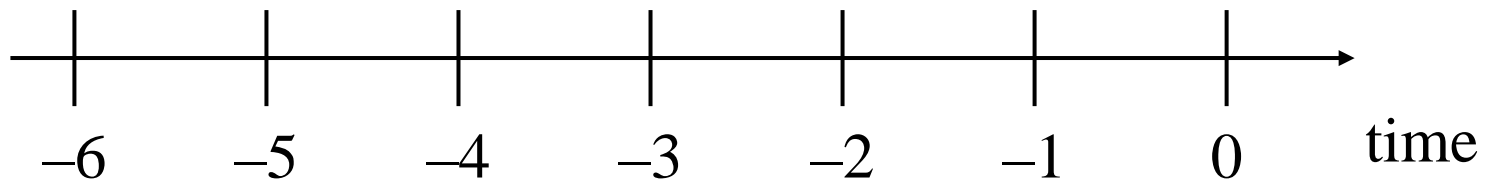
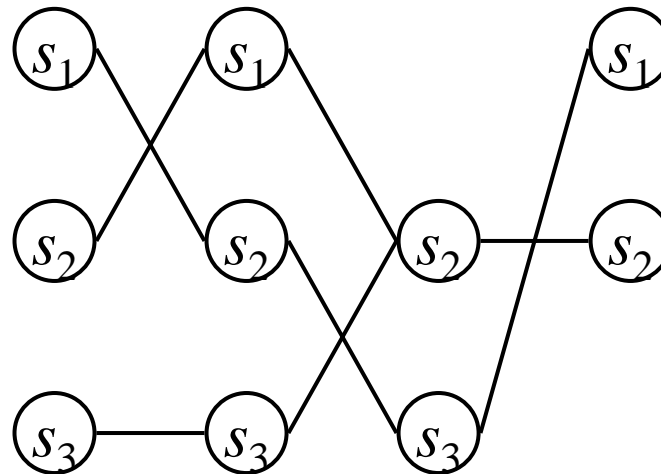
$$(\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda))$$

\Rightarrow return y ;

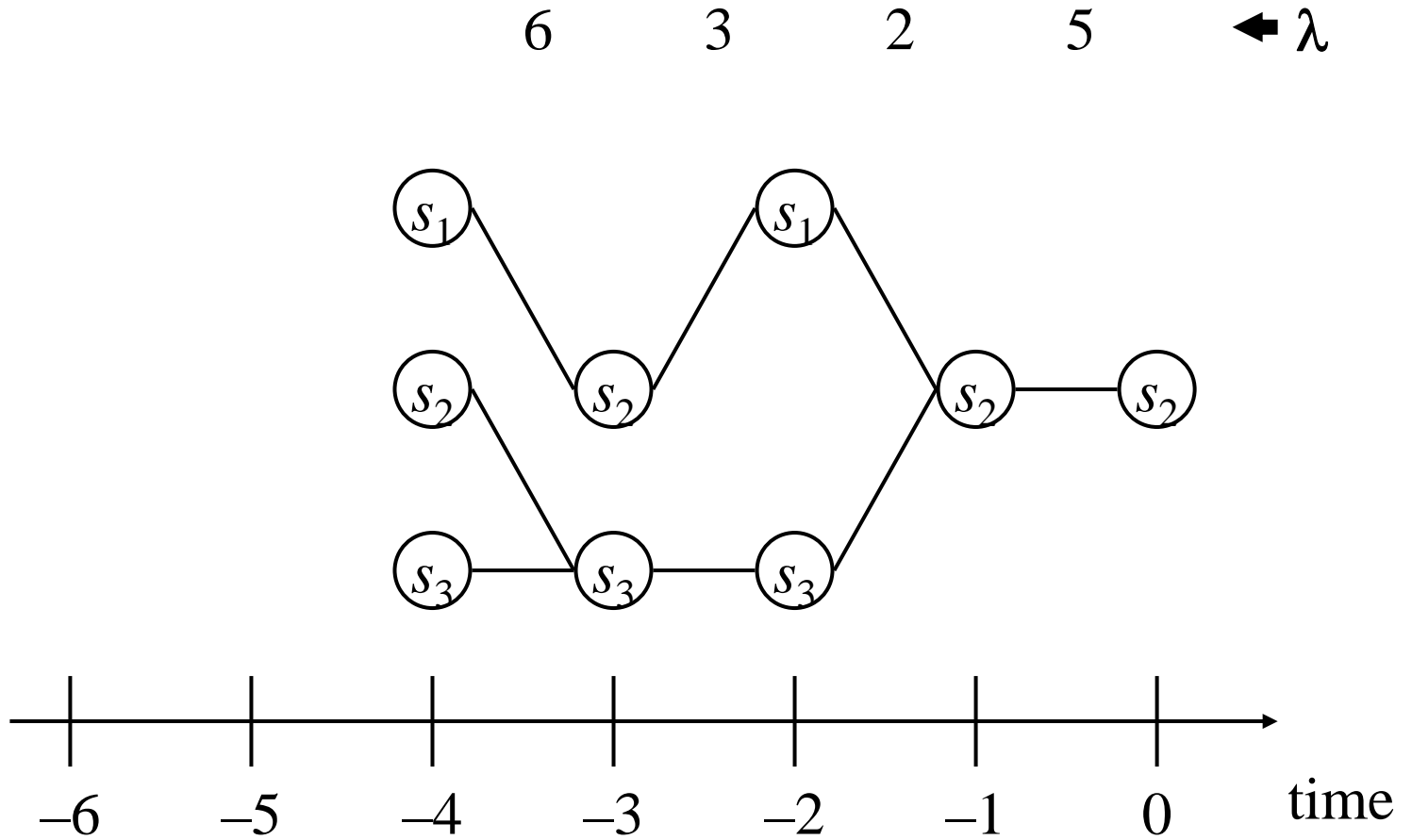
b. otherwise, set $T := T - 1$;

go to step 2.;

3 2 5 $\leftarrow \lambda$



Simulation from $T = -4$

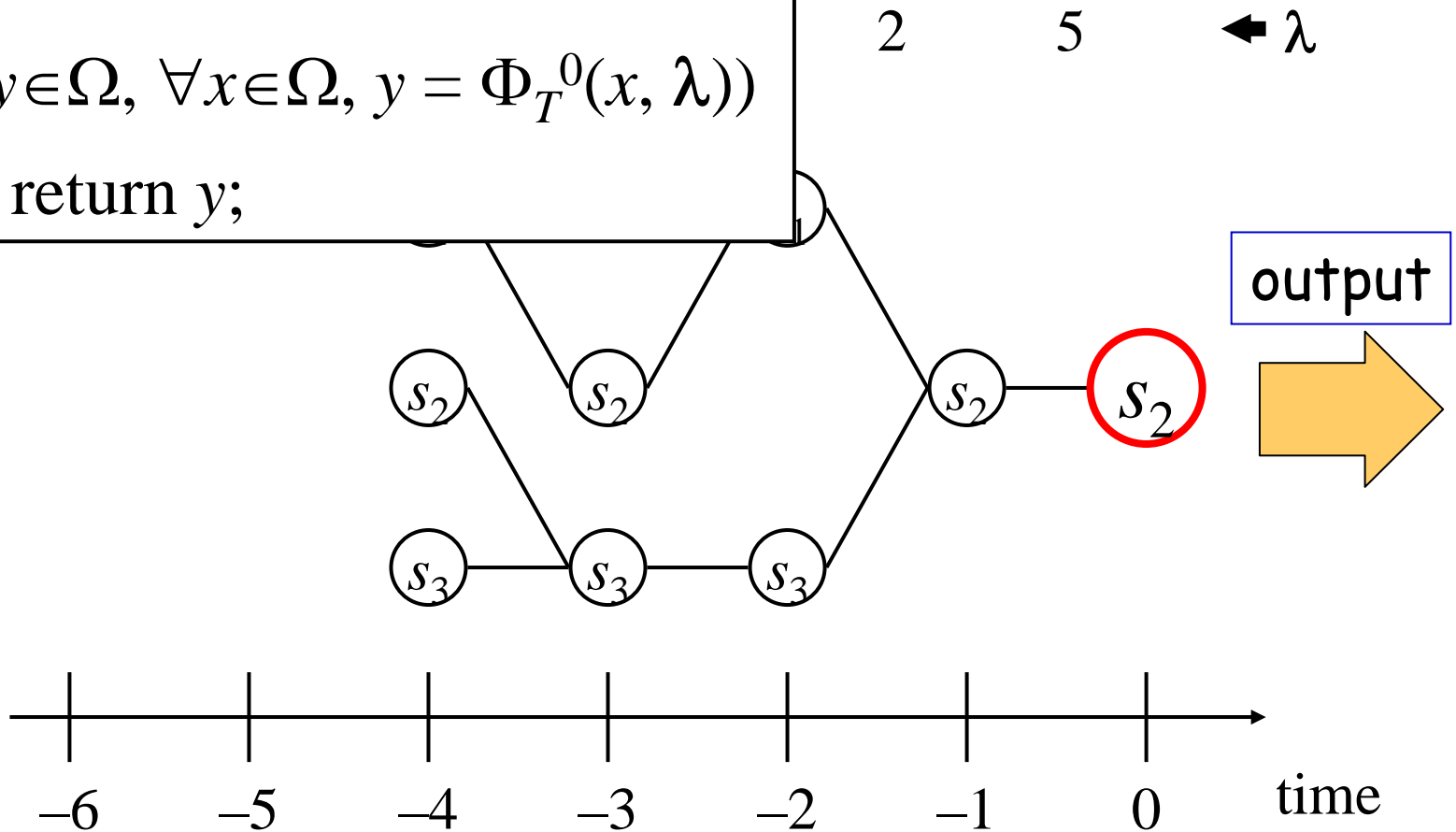


Simulation from $T = -4$

a. if **coalesce**

$$(\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda))$$

\Rightarrow return y ;



CFTP Algorithm and Theorem.

Markov chain MC : $\left\{ \begin{array}{l} \Omega: \text{finite state space} \\ \Phi_s^t(x, \lambda): \text{transition rule} \\ \text{ergodic} \end{array} \right.$

CFTP Algorithm

1. Set $T = -1$; set λ : empty;
2. Generate $\lambda[T], \dots, \lambda[T/2 - 1]$: random number;
Put $\lambda := (\lambda[T], \dots, \lambda[T/2 - 1], \lambda[T/2], \dots, \lambda[-1])$;
3. Start a chain from every element in Ω at period T , run MC with λ to period 0.
 - a. if **coalesce** ($\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda)$) \Rightarrow return y ;
 - b. otherwise, set $T := T-1$; go to step 2.;

CFTP Theorem

When CFTP Algorithm terminates, the returned value realizes the random variable from stationary distribution, **exactly**.

what is the idea of CFTP?

Idea of CFTP (Coupling From the Past)

- ◆ Suppose an ergodic chain from **infinite past**, imaginarily.
 - Present state (state at time 0) is EXACTLY according to the stat. dist.
- ◆ What is the present state?
 - Guess from the **recent random transitions**.
 - ⇒ Find the evidence of the present state.

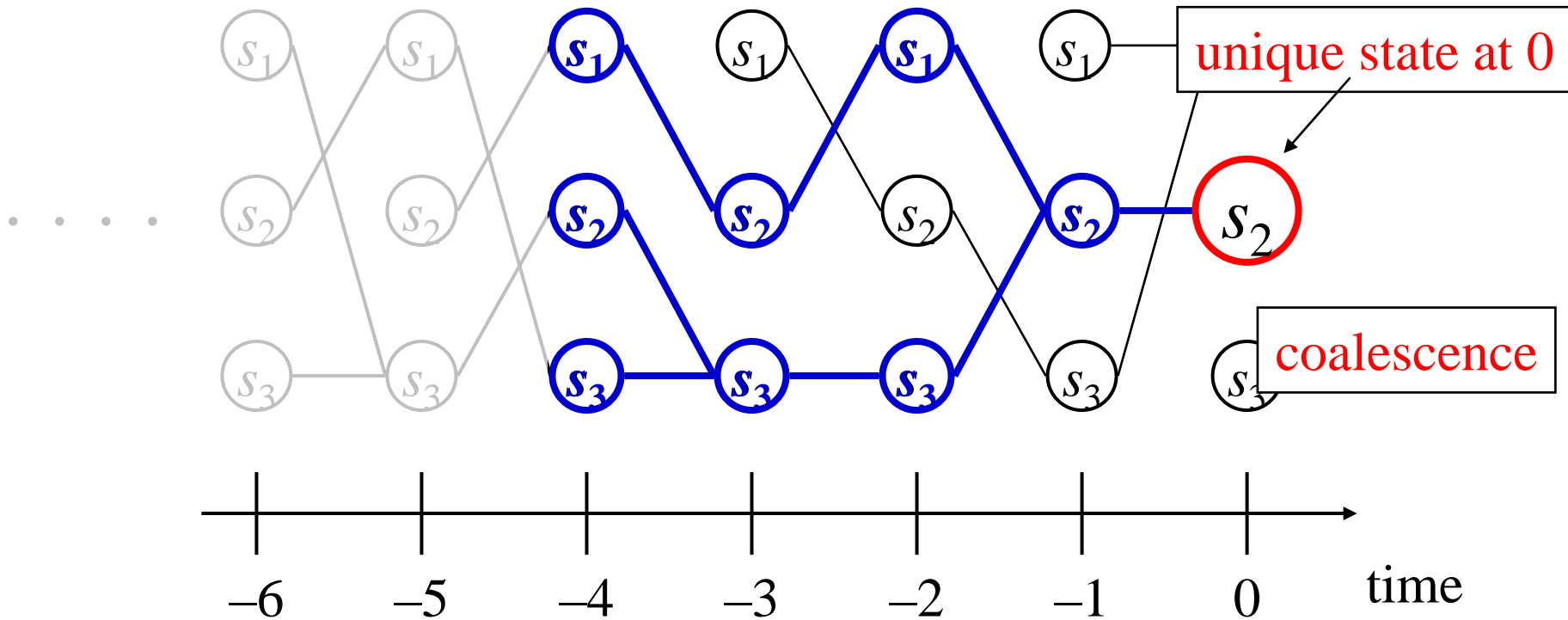
obtained by considering random numbers and transitions with an **update function**.

Figure of CFTP

Obtain the present state (time 0) of infinite transitions!!

Recent random numbers

4 1 6 3 2 5 ← λ



Then we can start chains at time -4 from all states with recent random numbers.

Fortunately, we obtain a unique state at time 0. we call this situation 'coalescence'

CFTP Algorithm and Theorem.

Markov chain MC : {

- Ω : finite state space
- $\Phi_s^t(x, \lambda)$: transition rule
- ergodic

However it is hard to start ...

CFTP Algorithm

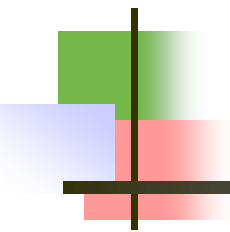
since we concern with huge state space

1. Set $T = -1$; set λ : empty;
2. Generate $\lambda[T], \dots, \lambda[T/2 - 1]$: random number;
Put $\lambda := (\lambda[T], \dots, \lambda[T/2 - 1], \lambda[T/2], \dots, \lambda[-1])$;
3. Start a chain from every element in Ω at period T , run MC with λ to period 0.
 - a. if **coalesce** ($\exists y \in \Omega, \forall x \in \Omega, y = \Phi_T^0(x, \lambda)$) \Rightarrow return y ;
 - b. otherwise, set $T := T-1$; go to step 2.;

CFTP Theorem

When CFTP Algorithm terminates, the returned value realizes the random variable from stationary distribution, **exactly**.

We cannot apply this algorithm, directly



-2: Perfect Sampler
for two-rowed contingency tables

[KM '06]

Rem. Markov chain for contingency tables [KM '06]

1. choose a **consecutive** pair of columns $(j, j+1)$ u.a.r. (prob. $1/(n-1)$)
2. change the values of cells in $(j, j+1)$ -th columns u.a.r. on possible states

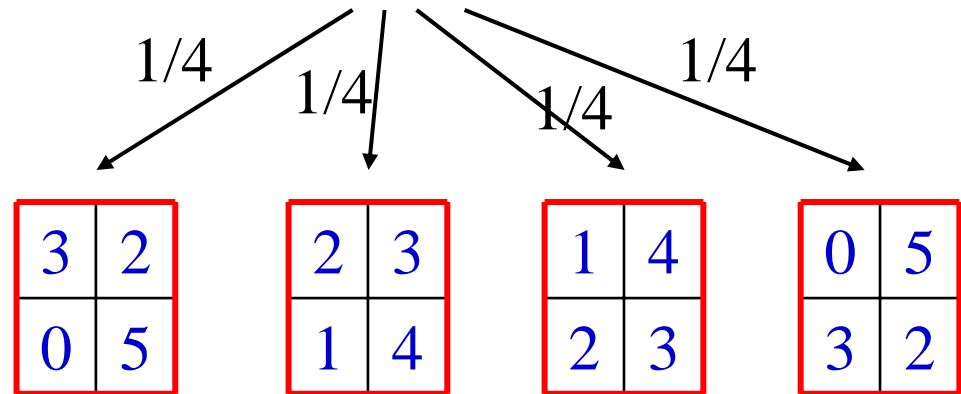
2	3	5
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3	7	10

+

$+k$	$-k$
$-k$	$+k$

=> preserve marginal sums

		j	$j+1$			
		↓	↓			
4	3	2	3	0	0	12
1	1	1	4	5	6	18
5	4	3	7	5	6	30



4 possible states

(requirement on non-negativity)

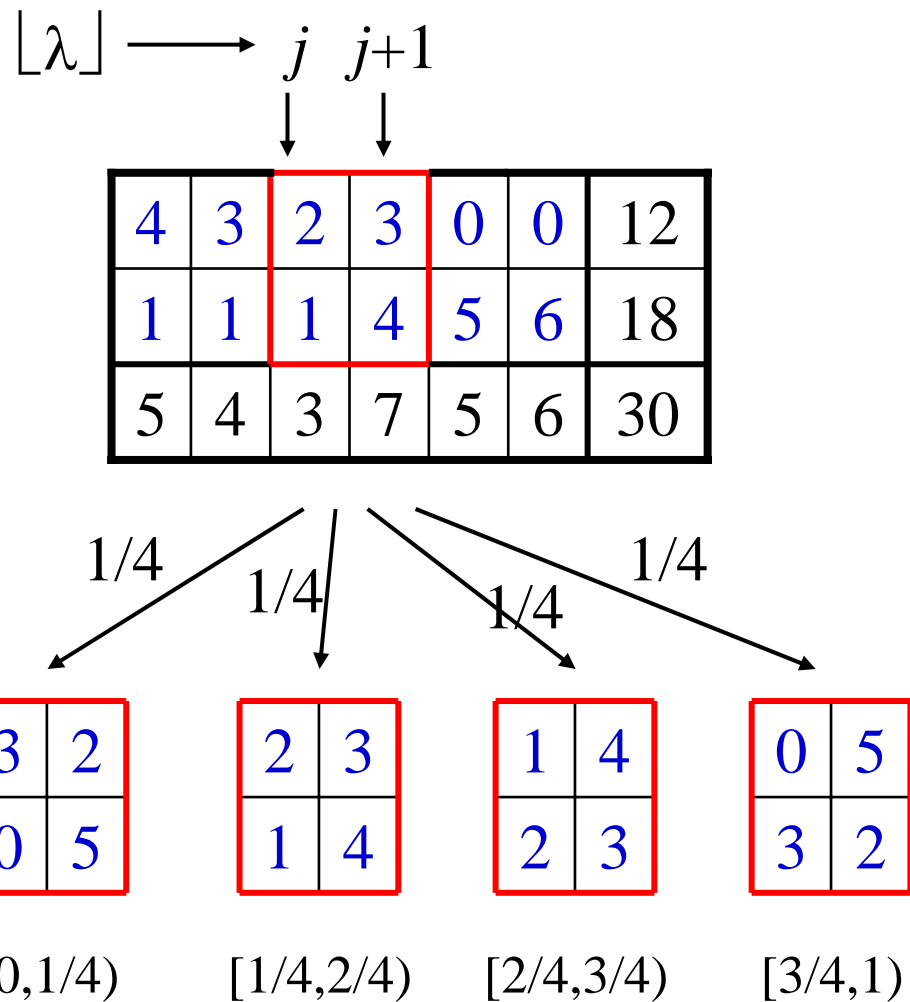
Update function [KM '06]

- generate random real $\lambda \in [1, n)$
- set $j = \lfloor \lambda \rfloor$
- set

$$X(1, j) = \max\{X'[1, j]\} - \lfloor \theta \lambda' \rfloor$$

➤ θ : #of possible states

➤ $\lambda' := \lambda - \lfloor \lambda \rfloor$



$$\lambda' := \lambda - \lfloor \lambda \rfloor$$

Sampling algorithm (monotone CFTP)

1. Set $T = -1$; Set λ : empty sequence;
2. Generate $\lambda[T], \dots, \lambda[-1]$ random number;
 put $\lambda := (\lambda[T], \dots, \lambda[T/2 - 1], \lambda[T/2], \dots, \lambda[-1])$;
3. Start chains from x_U, x_L at period T and simulate with λ until period 0;
 - a. if **coalesce** on $Y \Rightarrow$ return Y ;
 - b. otherwise, set $T := 2T$; go to 2;

5	4	3	0	0	0	12
						18
						30

We simulate just 2 chains

X_U : N-W rule

0	0	0	1	5	6	12
5	4	3	6	0	0	18
5	4	3	7	5	6	30

X_L : N-E rule

Them.

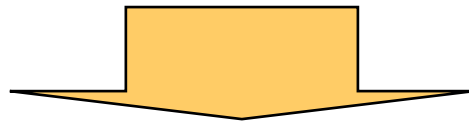
The algorithm returns a random vector EXACTLY according to a product form solution.

Key points of the theorem is ...

Claim

Coalescence from x_U and $x_L \Leftrightarrow$ Coalescence from all states

- Introduce a partial order on the state space.
- X_U and X_L are the max. and the min., respectively.
- Any transition keeps the partial order.



Our Markov chain is a **monotone** Markov chain

[Propp and Wilson 1996]

Def. cumulative sum vector

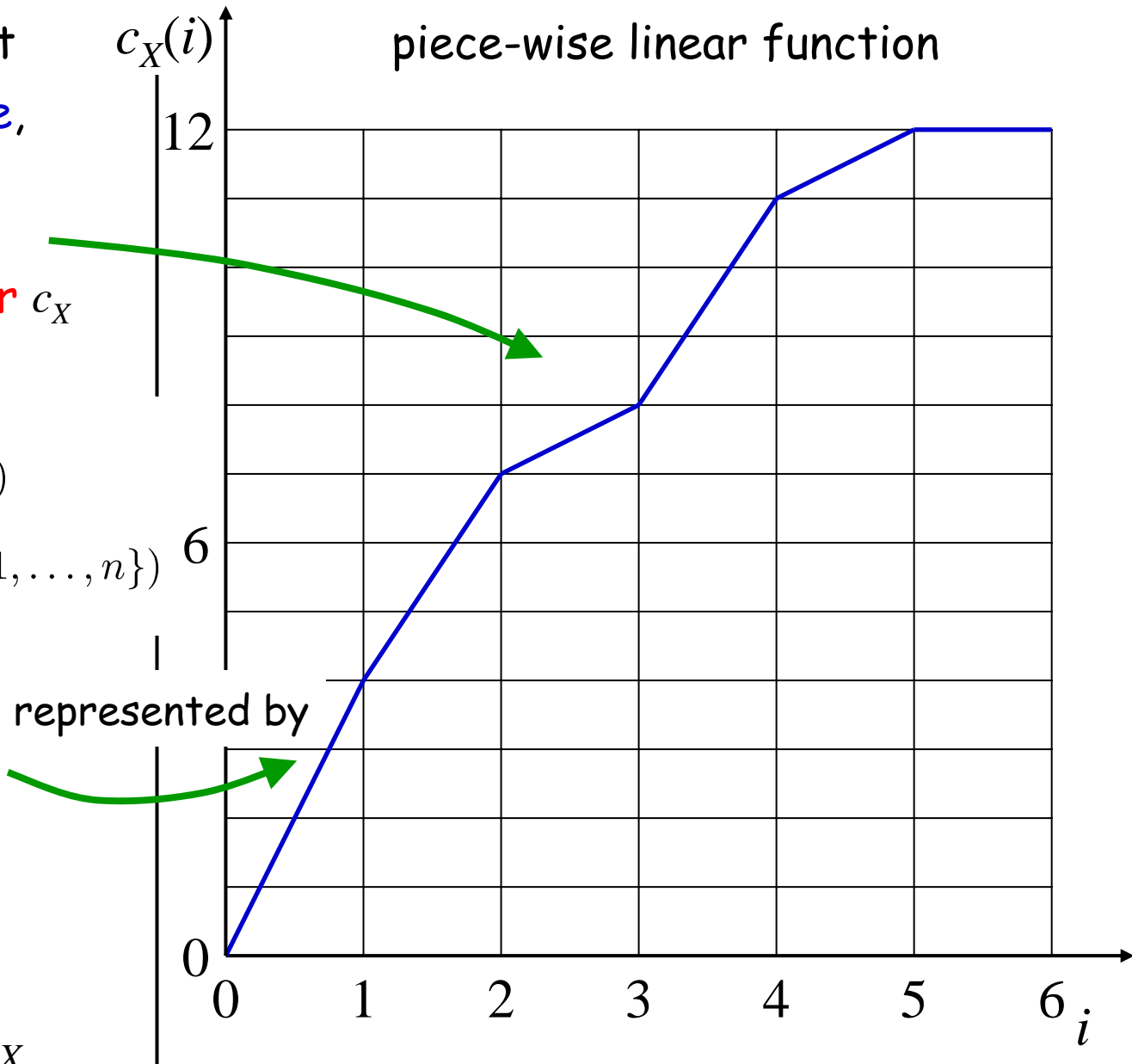
Consider to represent a $2 \times n$ table X by a **line**, which is a piece-wise linear function of **cumulative sum vector** c_X defined by

$$c_X(i) \stackrel{\text{def.}}{=} \begin{cases} 0 & (i = 0) \\ \sum_{j=1}^i X[1, j] & (i \in \{1, \dots, n\}) \end{cases}$$

e.g.,

4	3	1	3	1	0	12
1	1	2	4	4	6	18
5	4	3	7	5	6	30

➤ bijection: $X \rightarrow c_X$



transition (represented by a line)

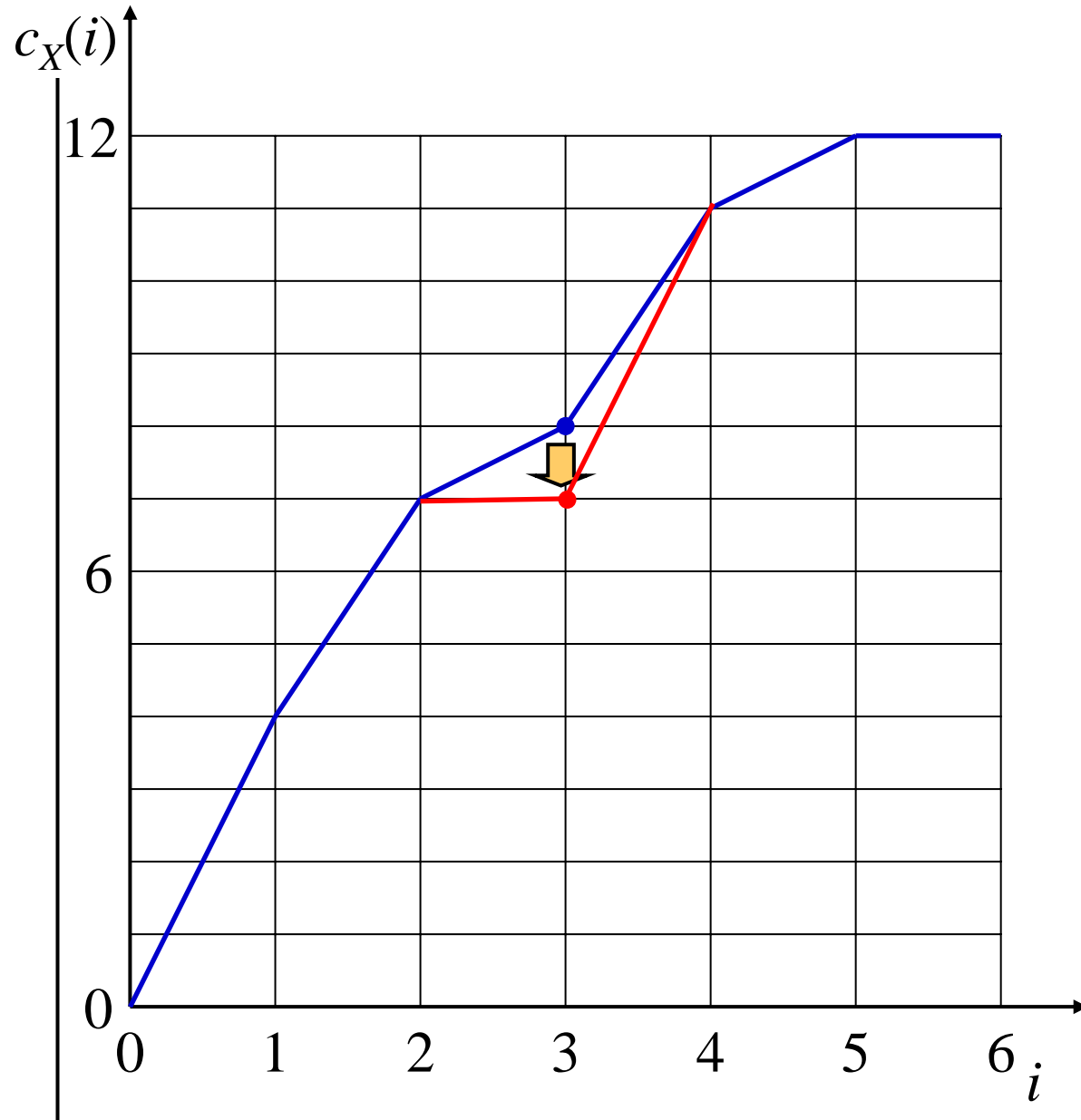
e.g., $\lambda = 3.1$

4	3	1	3	1	0	12
1	1	2	4	4	6	18
5	4	3	7	5	6	30



4	3	0	4	1	0	12
1	1	3	3	4	6	18
5	4	3	7	5	6	30

in the line representation
Choose an index, and
change the point
only at the index.



Def. Partial order

$$X \geq Y$$

$$\Leftrightarrow c_X(i) \geq c_Y(i)$$

$$(\forall i \in \{0, \dots, n\})$$

X

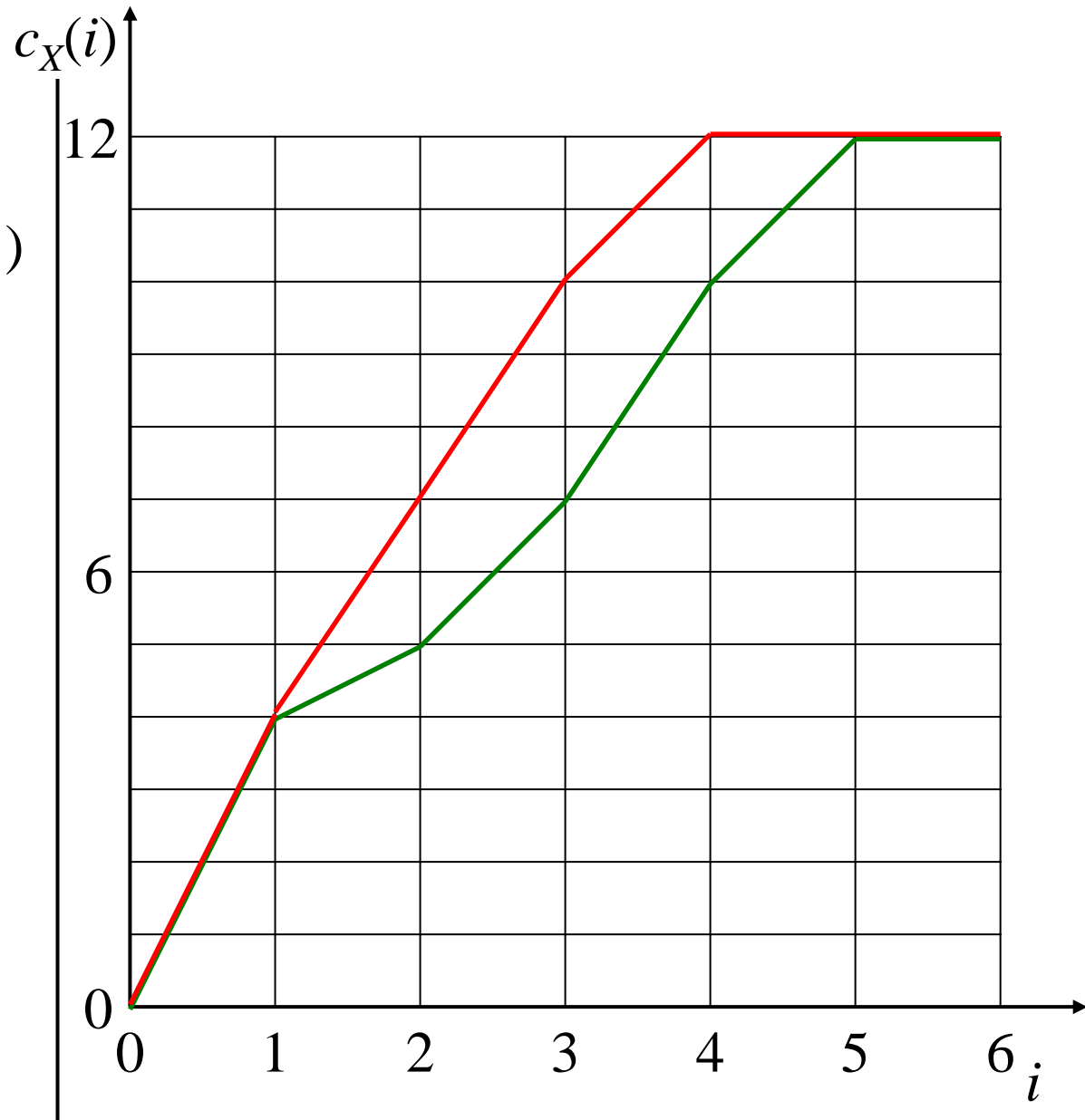
4	3	3	2	0	0	12
1	1	0	5	5	6	18
5	4	3	7	5	6	30

Y

4	1	2	3	2	0	12
1	3	1	4	3	6	18
5	4	3	7	5	6	30

$$X \geq Y$$

It means that **red** line is upper than **green**.



Max, Min on poset

5	4	3	0	0	0	12
0	0	0	7	5	6	18
5	4	3	7	5	6	30

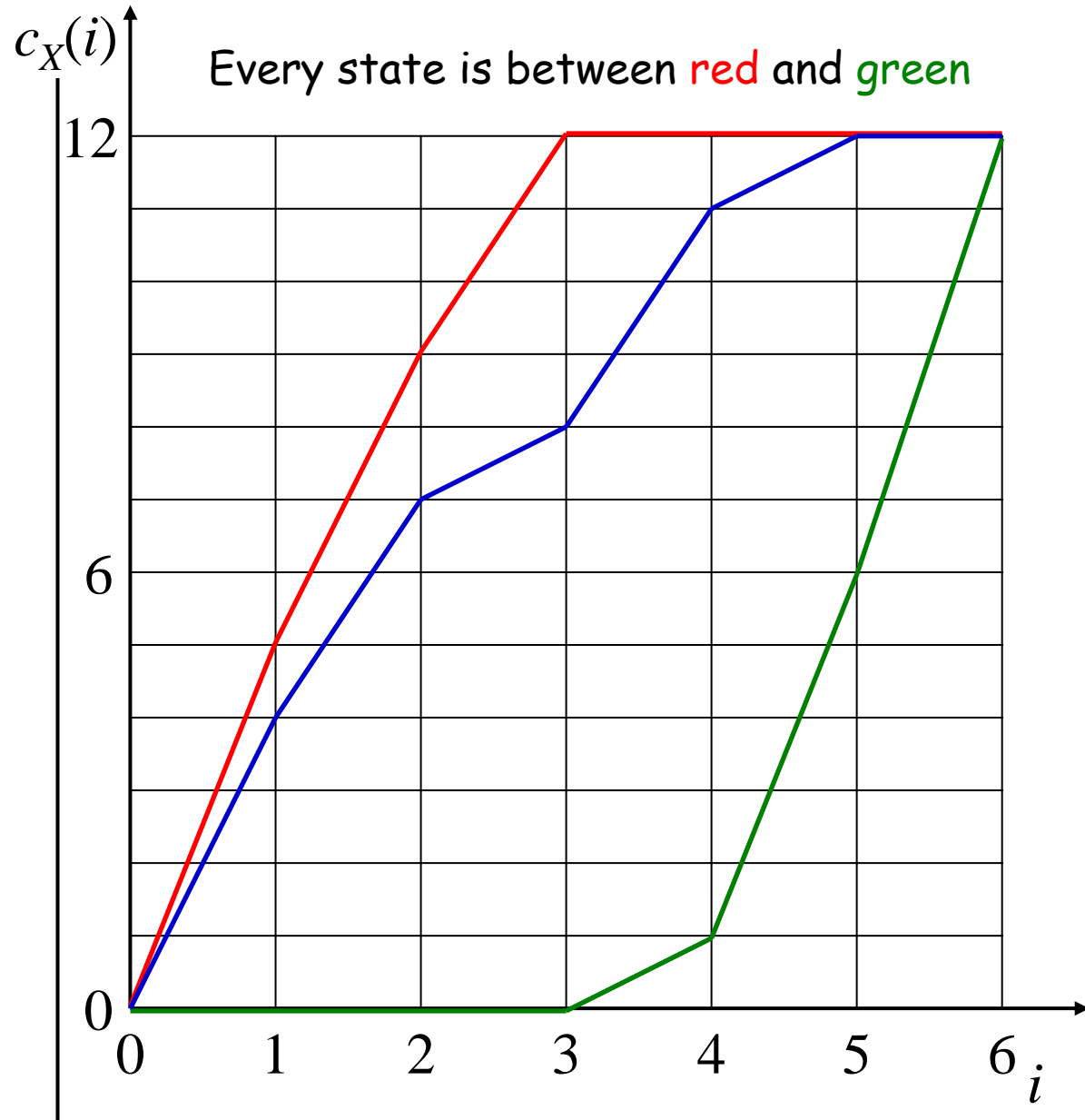
X_U : N-W rule

0	0	0	1	5	6	12
5	4	3	6	0	0	18
5	4	3	7	5	6	30

X_L : N-E rule

Lemma

$$X_U \geq \forall X \geq X_L$$



Key lemma

X'

4	3	3	0	2	0	12
1	1	0	7	3	6	18
5	4	3	7	5	6	30

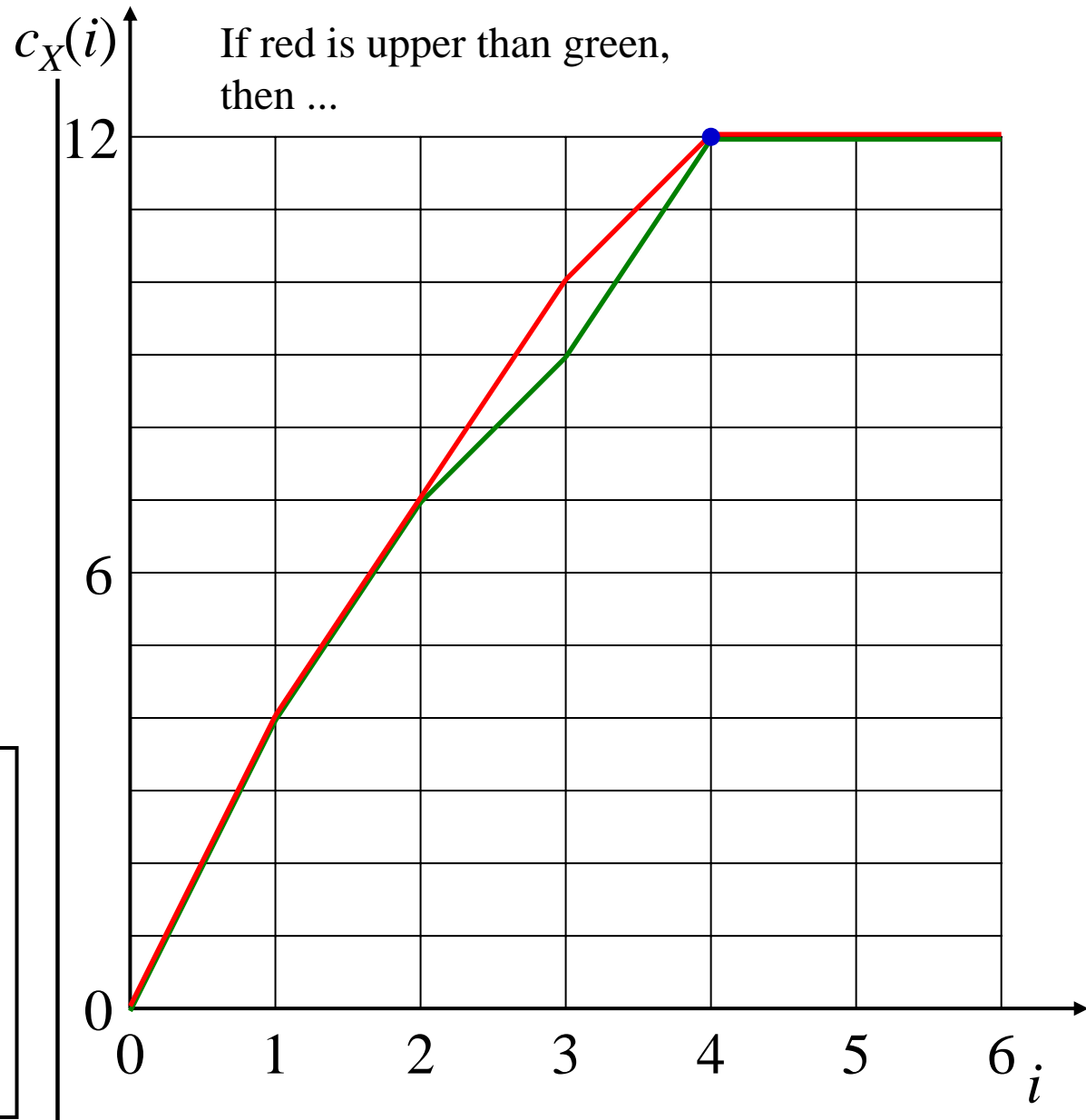
Y'

4	3	2	2	1	0	12
1	1	1	5	4	6	18
5	4	3	7	5	6	30

Lemma

Any transition keeps partial order i.e.,

$$\forall (X, Y) \text{ s.t. } X \geq Y, \\ \phi(X, \lambda) \geq \phi(Y, \lambda)$$



Key lemma

X'

4	3	3	0	2	0	12
1	1	0	7	3	6	18
5	4	3	7	5	6	30

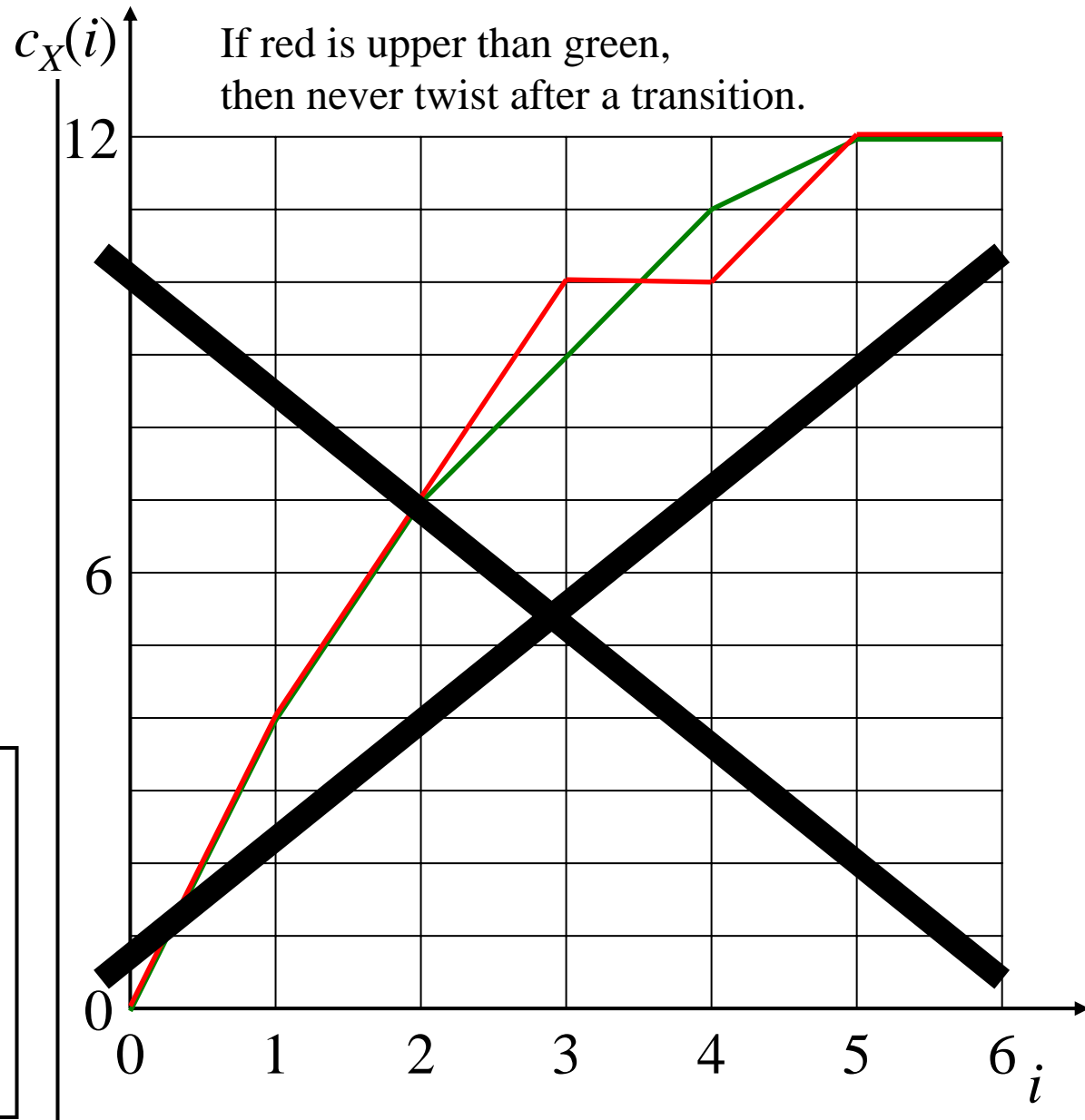
Y'

4	3	2	2	1	0	12
1	1	1	5	4	6	18
5	4	3	7	5	6	30

Lemma

Any transition keeps partial order i.e.,

$$\forall (X, Y) \text{ s.t. } X \geq Y, \\ \phi(X, \lambda) \geq \phi(Y, \lambda)$$

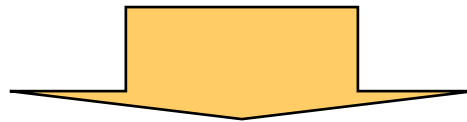


Key points of the theorem is ...

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Coalescence from x_U and $x_L \Leftrightarrow$ Coalescence from all states

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Our Markov chain is a **monotone** Markov chain

[Propp and Wilson 1996]

fig. of coalescence

every state is between

red line (= X_U) and green line (= X_L)

5	4	3	0	0	0	12
0	0	0	7	5	6	18
5	4	3	7	5	6	30

4	3	1	3	1	0	12
1	1	2	4	4	6	18
5	4	3	7	5	6	30

0	0	0	1	5	6	12
5	4	3	6	0	0	18
5	4	3	7	5	6	30

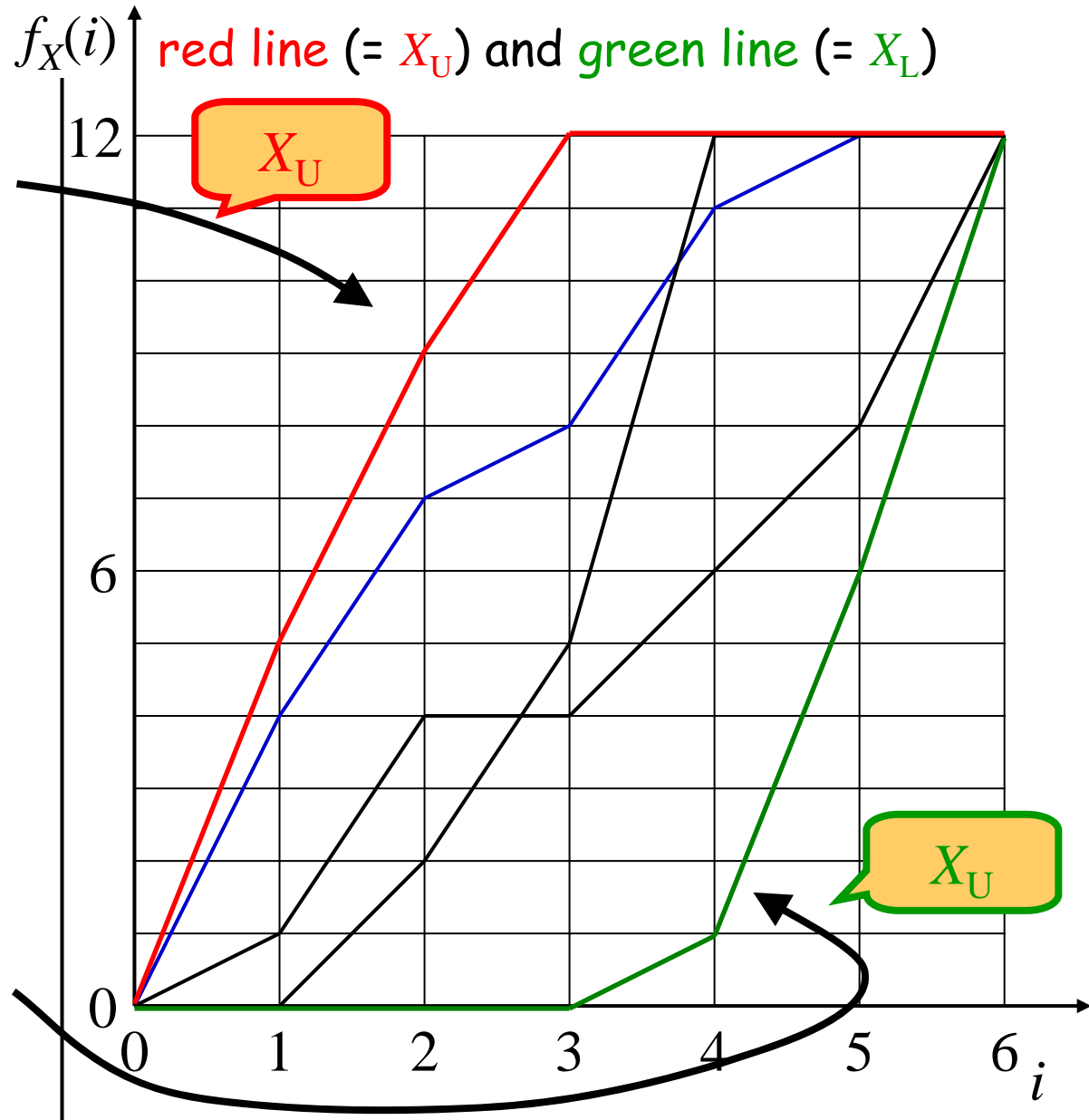


fig. of coalescence

any transition preserve part. order
 \Rightarrow every state is between red & green

5	4	0	3	0	0	12
0	0	3	4	5	6	18
5	4	3	7	5	6	30

4	3	0	4	1	0	12
1	1	3	3	4	6	18
5	4	3	7	5	6	30

0	0	0	1	5	6	12
5	4	3	6	0	0	18
5	4	3	7	5	6	30

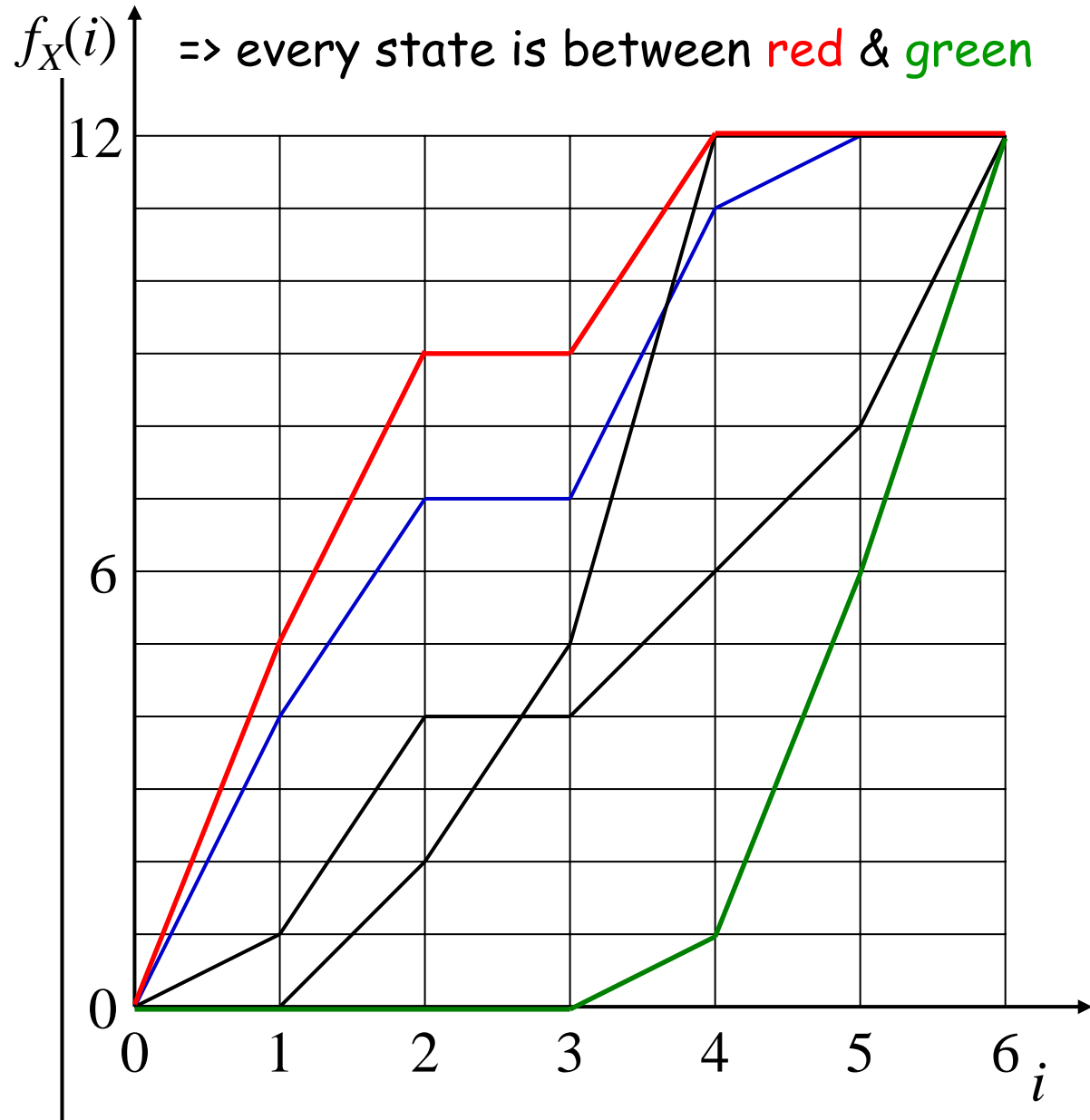


fig. of coalescence

5	4	0	2	1	0	12
0	0	3	5	4	6	18
5	4	3	7	5	6	30

4	3	0	3	2	0	12
1	1	3	4	3	6	18
5	4	3	7	5	6	30

0	0	0	4	2	6	12
5	4	3	3	3	0	18
5	4	3	7	5	6	30

any transition preserve part. order

=> every state is between red & green

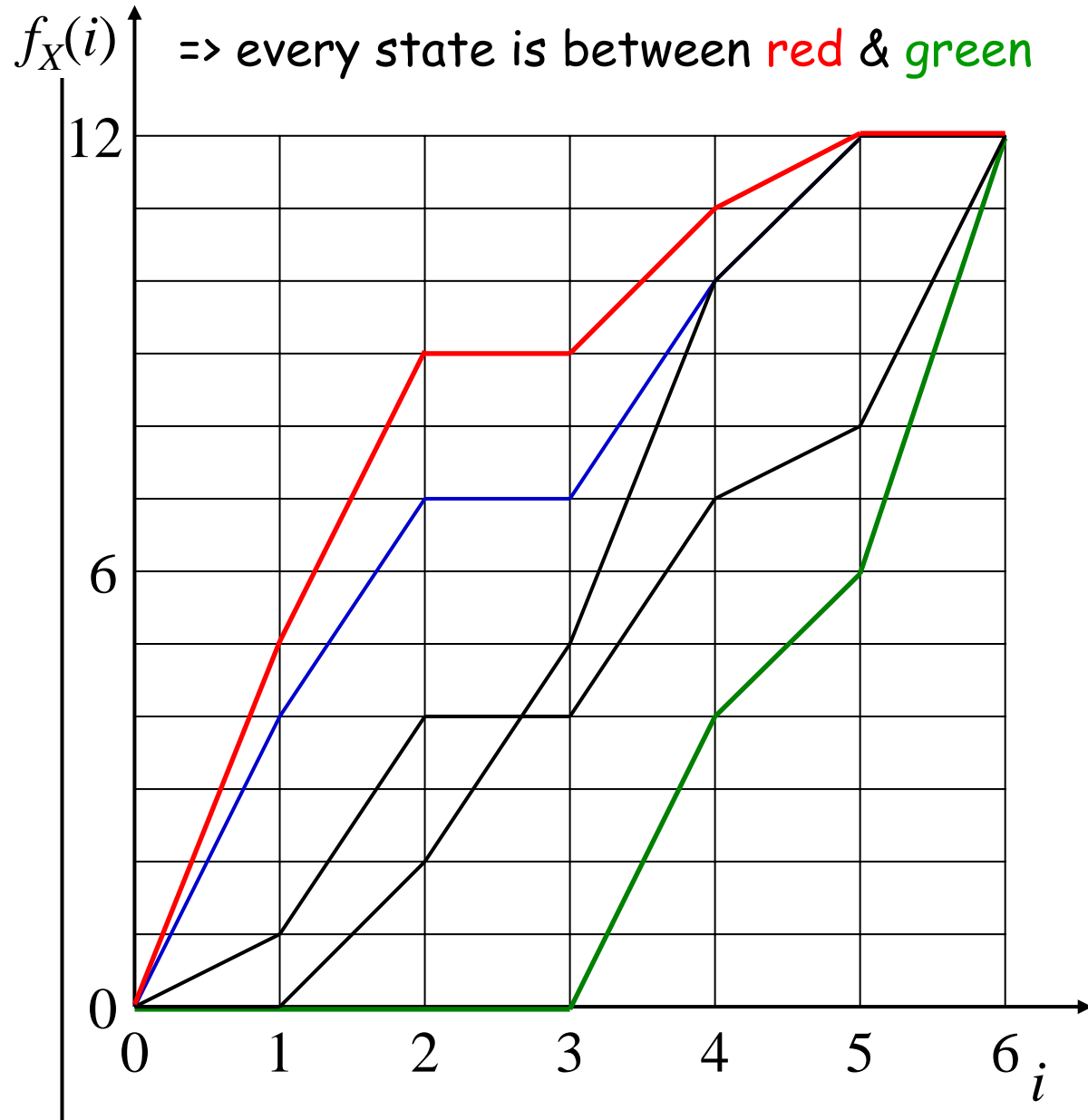


fig. of coalescence

any transition preserve part. order

=> every state is between red & green

3	3	2	1	2	1	12
2	1	1	6	3	5	18
5	4	3	7	5	6	30

3	3	1	2	2	1	12
2	1	2	5	3	5	18
5	4	3	7	5	6	30

1	2	2	3	2	2	12
4	2	1	4	3	4	18
5	4	3	7	5	6	30

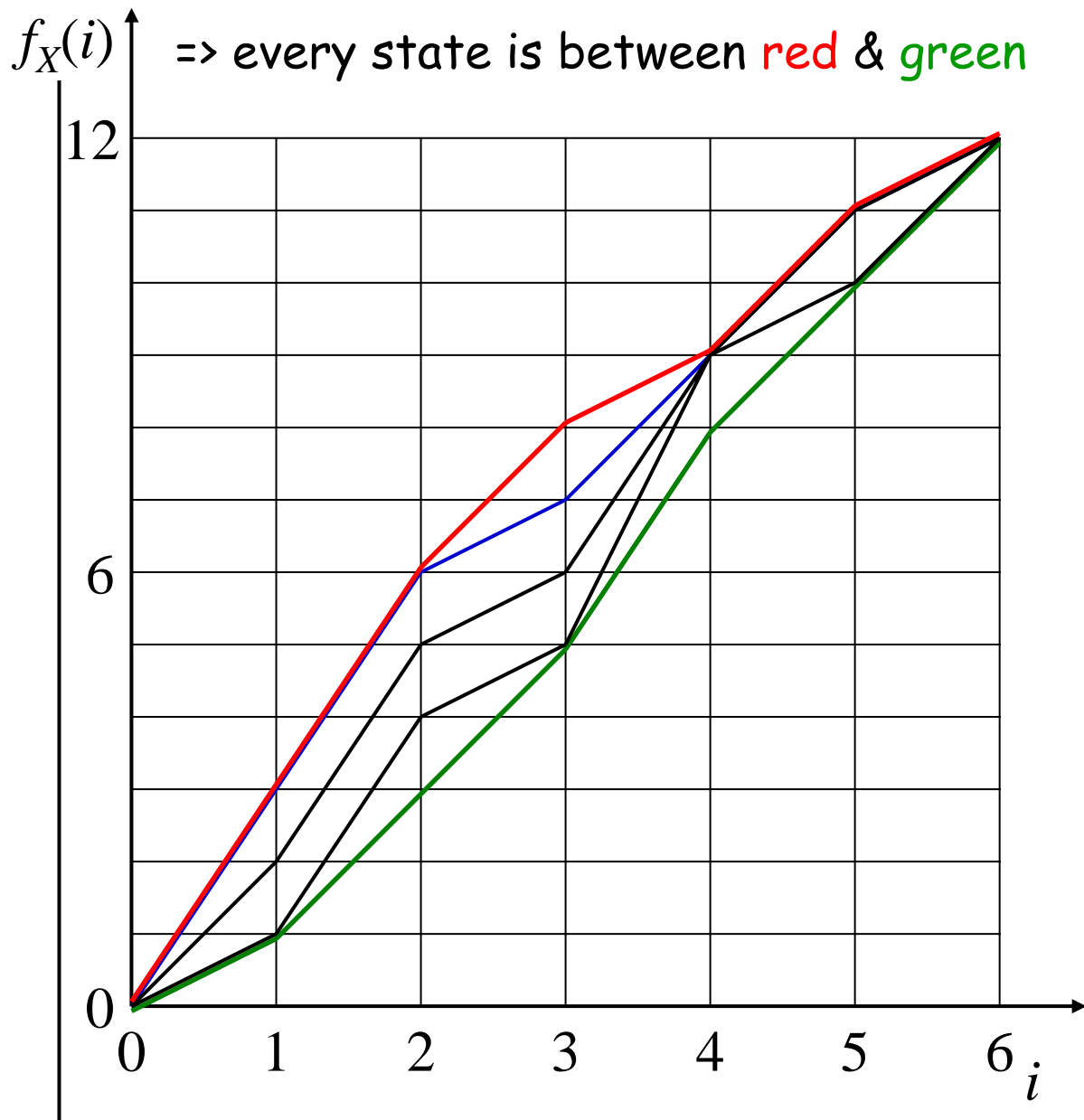
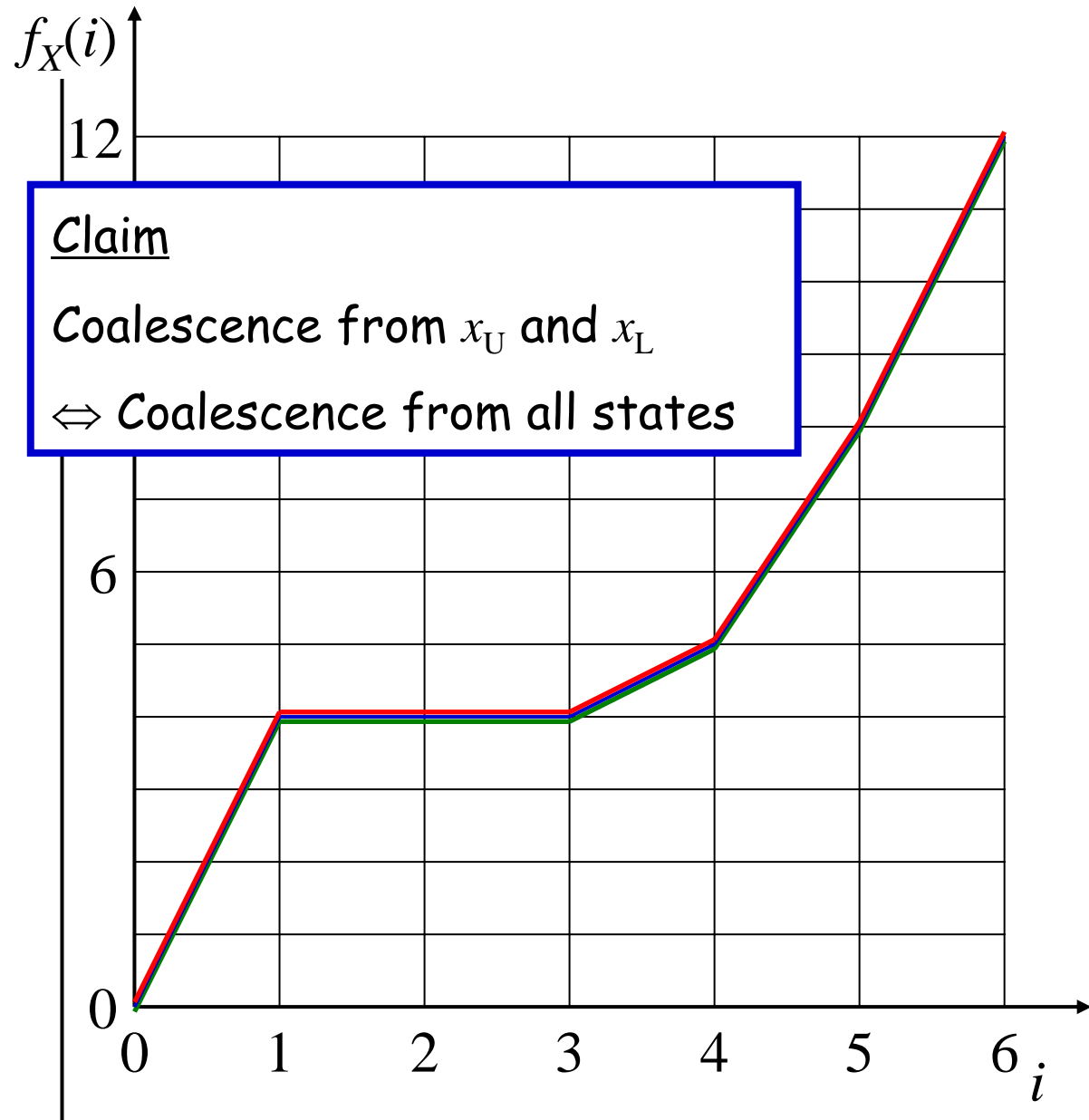


fig. of coalescence

4	0	0	1	3	4	12
1	4	3	6	2	2	18
5	4	3	7	5	6	30

4	0	0	1	3	4	12
1	4	3	6	2	2	18
5	4	3	7	5	6	30

4	0	0	1	3	4	12
1	4	3	6	2	2	18
5	4	3	7	5	6	30





-1: Concluding Remark

Expected running time of our perfect sampler

Condition

column sum vector s satisfies

$$s_1 \geq s_2 \geq \dots \geq s_n$$

Claim

Expected coalescence time = $O(n^3 \ln(n \cdot K))$.

n : # of rows

K : sum total in table

➤ Omit the proof

• Expected running time of CFTP algorithm =

(T_* : **coalescence time**)

• Coalescence time of monotone CFTP (Propp and Wilson '96)

➤ $E[T_*] \leq 2\tau(1 + \ln D)$

(τ : **mixing rate**, D : the distance of max. and min.)

• Mixing rate of our chain

➤ $\tau = n^2(n-1) \ln(n \cdot K)$, $D \leq (n \cdot K)$ (by **path coupling**)

✧ **special distance**

Single server model

Discussion

monotone Markov chain

- ✓ Ising model
 - restoration of mono-chromatic pictures
 - Potts model Hard-core model
- ✓ tiling
- ✓ 2-rowed contingency tables
- ✓ queueing network

Another perfect sampling algorithm

- ✓ Rooted spanning tree

Improvement of memory space

- Read once algorithm [Wilson 2000]

Reference

- O. Haeggstroem,
"Finite Markov Chains and Algorithmic Application,"
London Mathematical Society, Student Texts, 52,
Cambridge University Press, 2002.
- 来嶋秀治, 松井知己, "完璧にサンプリングしよう!"
オペレーションズ・リサーチ, 50 (2005),
第一話「遥かなる過去から」, 169--174 (no. 3),
第二話「天と地の狭間で」, 264--269 (no. 4),
第三話「終りある未来」, 329--334 (no. 5).

<http://www.simplex.t.u-tokyo.ac.jp/~kijima/>

(来嶋のHPの"資料"からダウンロード可能)

Future works

- To apply the monotone CFTP to sampling-hard objects
 - ⇒ Design a Markov chain
 - ⇒ Design a perfect sampler
 - ⇒ Estimate the coalescence time
- $m \times n$ contingency tables
- New algorithm for Perfect Sampling



0. The end

— all of your views coalesce.

Thank you for the attention.